



Development of UAV observation technology in NCU

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What is FALCON?

- **FALCON (Facility of Aerial Low-Cost Observational Network)** is an infrastructure to facilitate the atmospheric research community's need to fill the gap in hardware/firmware development related to unmanned aerial system (UAS) use.

For more information, please check out our poster and website

<http://falcon.atm.ncu.edu.tw>

FALCON
Facility of Aerial Low-Cost
Observational Network

FALCON Home People Facilities Research News

Highlights

Producing leaders in Unmanned Aerial Systems for Atmospheric Research
The Falcon team provide hands-on experience to students interested in UAVs and help solve different UAV industry applications. So far, Falcon team has completed hundreds of UAV missions.

FALCON Video

The fire fighter is a FALCON joined project to real-time monitoring fire accidents. Our technology can also apply to forest fire and biomass burning activities.

Drone Fighter

0:00 / 0:49

Research Goals

Weather
Aerosol
Radiation
Fire
Wind
AI



What FALCON do?

- Weather Measurement





What FALCON do?

- Commercial Application





What FALCON do?

- **UAV education**

1. We provide UAV experiencing program for high school to under graduated students.
2. We also provide drone flight training, including, operational rules, understanding airspace, aircraft technology and how to become a certified remote pilot.



FALCON's UAS



850V6



Sky-surfer X8



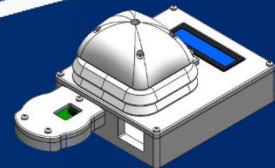
Skywalker X8



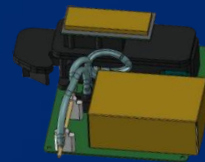
Red Falcon

Type	Hexacopter	Fixed-wing	Fixed-wing	Fixed-wing
Material	Aluminium alloy	EPO	EPO	Aircraft plywood
Power	Li-Po battery	Li-Po battery	Li-Po battery	Li-Po battery
Max. Payload	2 kg	0.1 kg	1 kg	2.5 kg
Endurance time	20-30 minute	40-60 minute	60-90 minute	60-90 min
Max. Flight level	1.5 km	5 km	5 km	5 km
Instrument	Aerobox / POPS / Windsond	Windsond	Aerobox / POPS / Windsond	Aerobox / POPS / Windsond and more
Cruising speed	3-4 ms ⁻¹	20-30 ms ⁻¹	30-40 ms ⁻¹	50-60 ms ⁻¹
Max. Takeoff Weight	6.5 kg	1.2 kg	2.4 kg	8 kg

FALCON sensor family

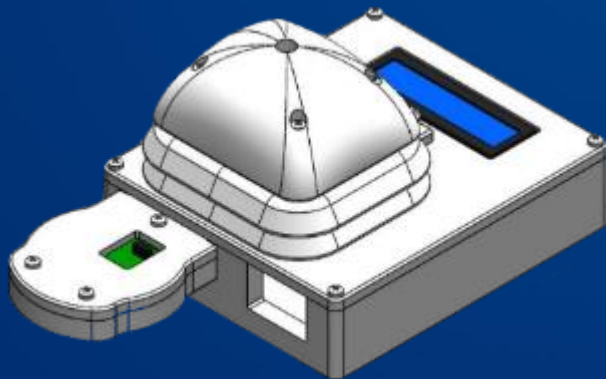


Type	Sensor/Module/Instrument	Parameter
Meteorology	temperature and humidity sensors	T, RH
	pressure sensors	P
	High-resolution wind field module	WD, WS
	2D Sonic wind sensor (FT technology)	WD, WS
	Radiation (EKO MS80s, MS01, SP Lite)	Radiation flux
Aerosol	POPS (NOAA)	Particle size distribution
	Low cost PM2.5 sensor (G3 and G5)	PM mass
	Black Carbon (AE51 and MA200)	BC conc.
Gases	trace gas and greenhouse gas sensors (CO, O ₃ , CO ₂ , CH ₄)	Mixing ratio
Imagery	Real-time view and thermal imaging module	VIS Image
	FLIR thermal camera (fire one)	IR image



FALCON sensor family

Aerobox



- Aerobox is designed and developed by our laboratory.
- Aerobox can expand and add a variety of sensors such as PM_{2.5}, CO, T, RH, GPS sensor.



Control board



PM_{2.5}, CO, T, RH, GPS sensor

FALCON sensor family

Aerosond

- Aerosond is a lower troposphere sounding system.
- Measuring the T, RH, P, wind, PM_{2.5} profiles within 10 km above ground level height.



Main circuit board

model	Aerosond v0
Size	5 x 2.2 x 4 cm
Weight	57.2 g
MCU module	Atmel 328P AU
RF module	LoRa 433
GPS module	NMEA
Power supply	Typ:5.0VDC; Min:4.5VDC; Max: 5.5VDC
Operation Temperature	-40 ~ 85 °C

PM_{2.5} sensor

model	Plantower PMS5003 G5
Size	5 X 2.2 X 4 cm
Effective Range	0~500 µg m ⁻³
Resolution	1 µg m ⁻³
Response Time	1 sec
Uncertainty	±10% @ 100~500 µg m ⁻³ ; ±10 µg m ⁻³ @ 0~100 µg m ⁻³
Operation Temperature	-10~+60 °C

Pressure sensor

model	MPL3115A2
Size	0.3 x 0.5 cm
Effective Range	20-110 kPa
Resolution	0.25 Pa
Response Time	0.1 s
Uncertainty	± 0.4 kPa
Operation Temperature	-40~85 °C

Temperature sensor

model	SHT31
Size(cm)	0.24 x 0.24
Effective Range	Depend on RF module
Resolution	0.015
Response Time	0.25 s
Uncertainty	± 0.3 °C
Operation Temperature	-40~90 °C

RH sensor

model	SHT31
Size	0.24 X 0.24 cm
Effective Range	Depend on RF module
Resolution	0.01
Response Time	0.25 sec
Uncertainty	± 2 %
Operation Temperature	-40~90 °C

FALCON sensor family

Buoyancy meter



FALCON sensor calibration facility

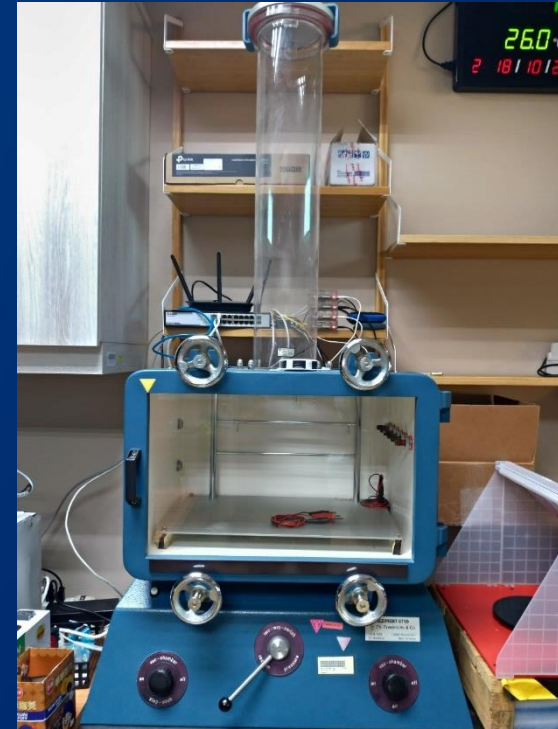
CO₂, CH₄, and zero air chamber



Humidity and Temperature chamber

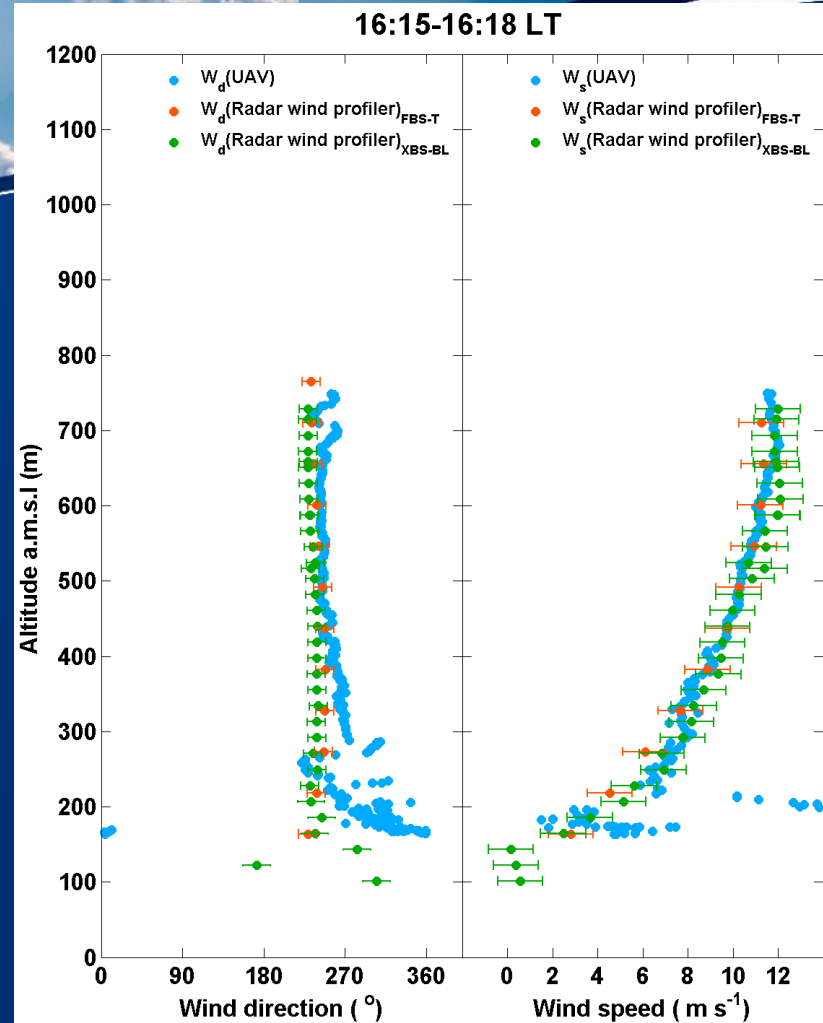
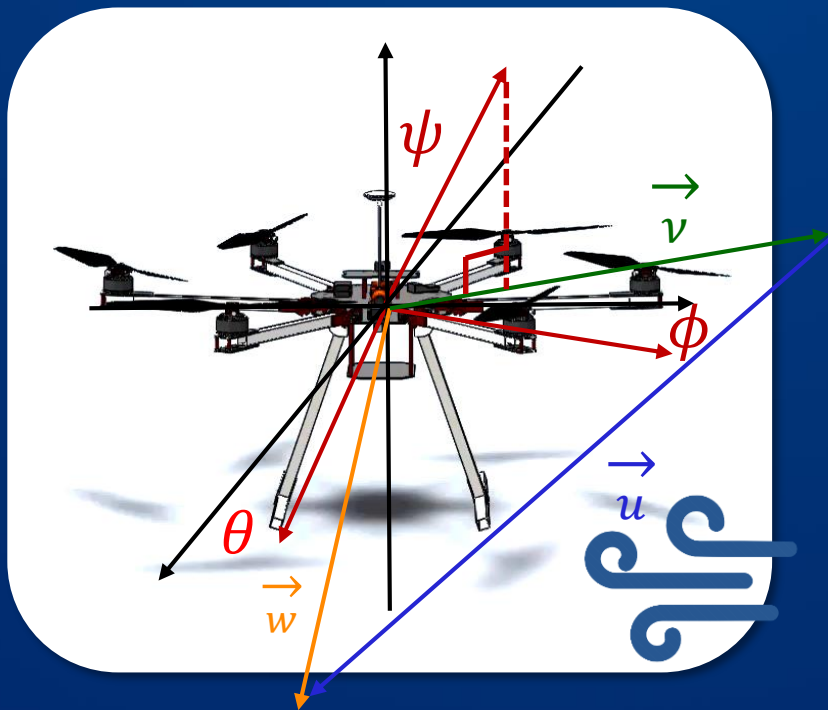


Pressure chamber



FALCON data inversion

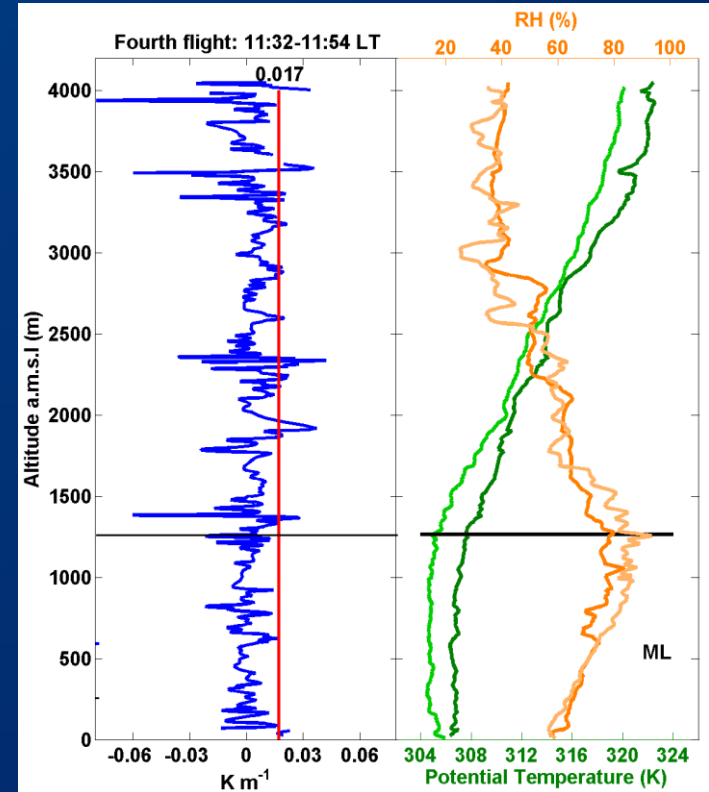
Wind speed and direction inversion



FALCON data inversion

PBL (or mixing layer) height detection

1. There is a temperature inversion layer between the mixed layer and the free atmosphere, so it can be assumed to be the height of the boundary layer.
2. The maximum gradient position of the vertical change of relative humidity.
3. The closest location of the dew point temperature and the temperature curve.
4. Select the gradient of the virtual potential temperature ($\frac{\partial \theta_v}{\partial z}$) is more than $+0.017 \text{ K m}^{-1}$ and then choose the nearest zero position.



FALCON Advantage

- Self-developed aircraft and sensors
- From 2014, the team began to develop atmospheric drone profile observations.
- Enriched atmospheric observation flight experience (more than 300 missions).
- Rich international cooperation and industry-university cooperation experience.



Faculty of Aerial Low-Cost
Observational Network

Test field for the development of atmospheric UAV System

Special permission
for flying airspace

Ground-based
remote sensing

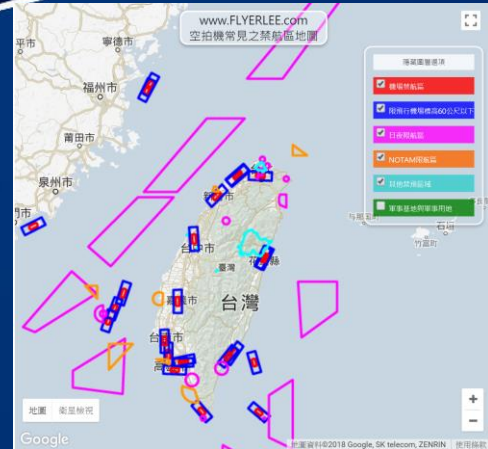


Flight training
and teaching

Industry and official
cooperation

What is the challenge of FALCON ?

1. **Airspace application**
2. **Aircraft registration**
3. **Automatic charging system and automatic flight (AI system can distinguish bad weather)**
4. **Integrate observational data with a combination of forecasting systems and data assimilation**



2018-2019 7SEAS/Chiang Mai UAV exp.



Measurements:

T, RH, P, wind, solar flux, aerosol size distribution, PM_{2.5} mass



(1195 m)

Doi Ang Khang

Myanmar border

Thailand

17 km



Measurements:

T, RH, P, wind, solar flux, PM_{2.5} mass, PM_{2.5} optical properties

Fang UAV site

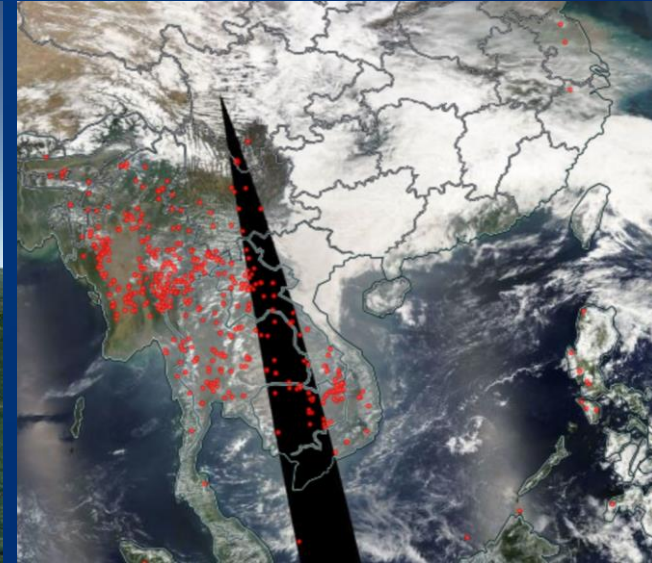
(468 m)

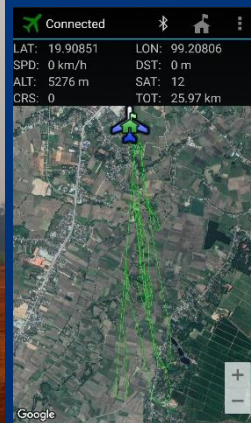


Measurements:

T, RH, P, wind, solar flux, PM_{2.5} mass, Ground-based remote sensing

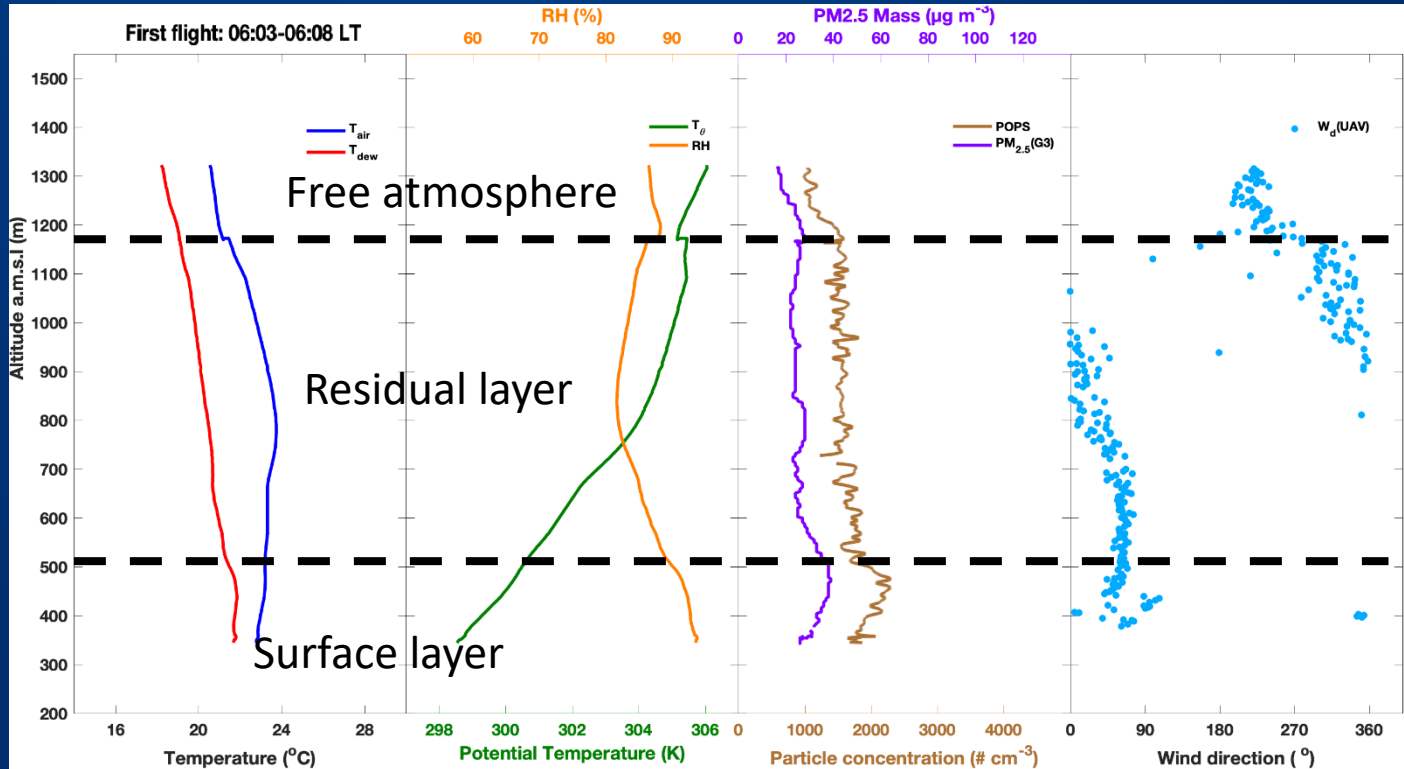
US Dept of State Geography
Image Landsat / Copernicus
Image © 2018 CNES / Airbus
Image © 2018 DigitalGlobe





2018-2019 7SEAS/Chiang Mai UAV exp.

May 19, 2018 6:00

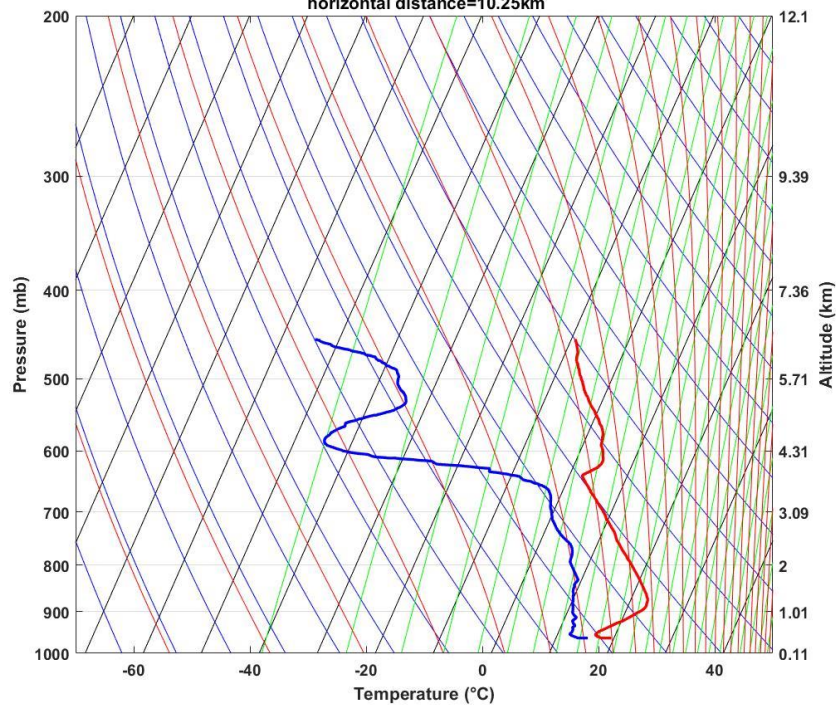


2019 7-SEAS泰國清邁觀測實驗

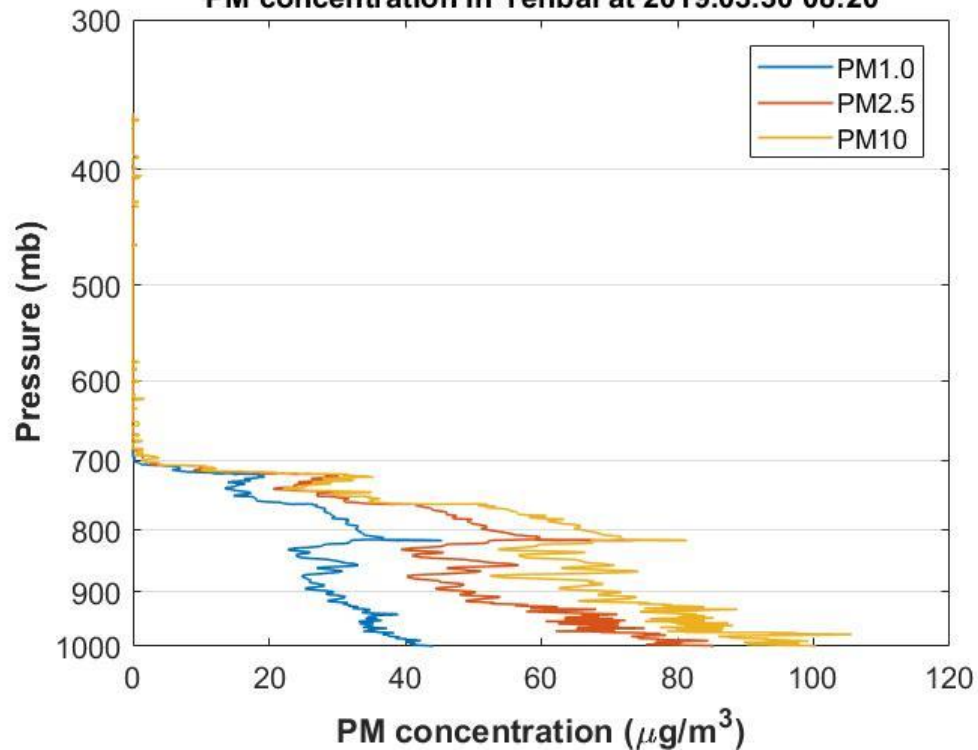


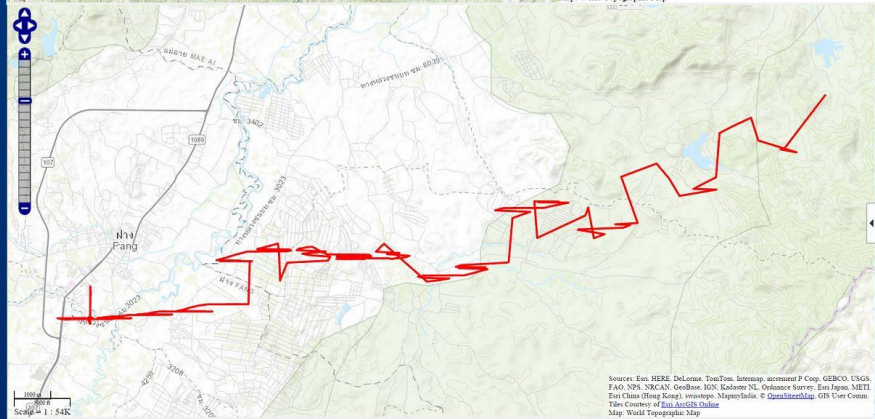
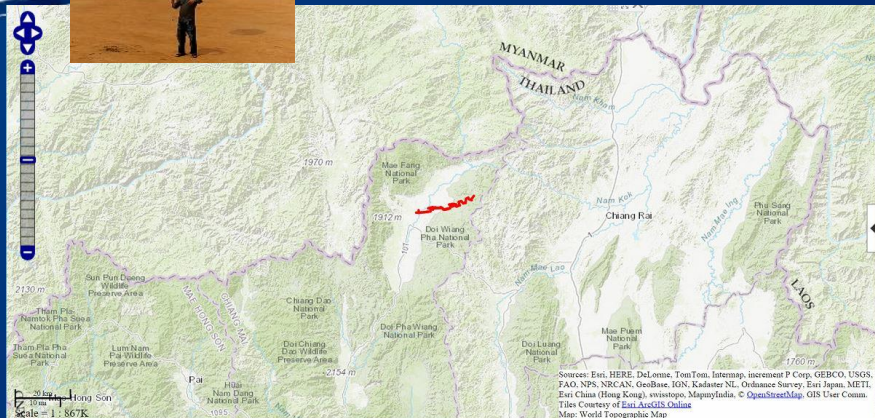
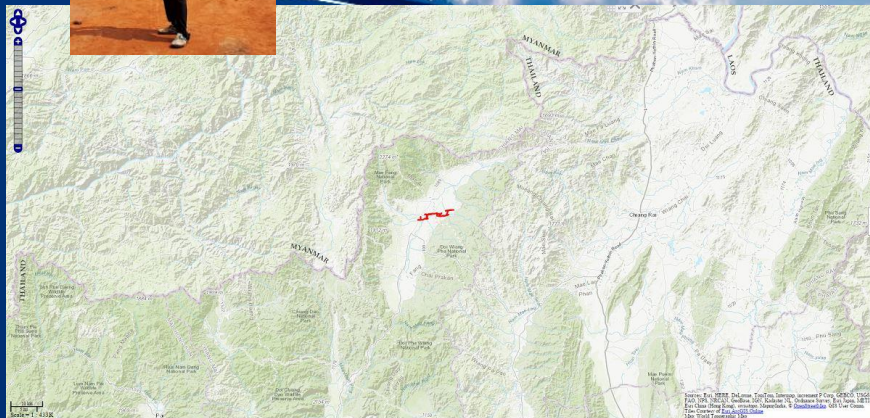


Skew T in Fang at 2019.03.16 08:00
horizontal distance=10.25km



PM concentration in Yenbai at 2019.03.30 08:20

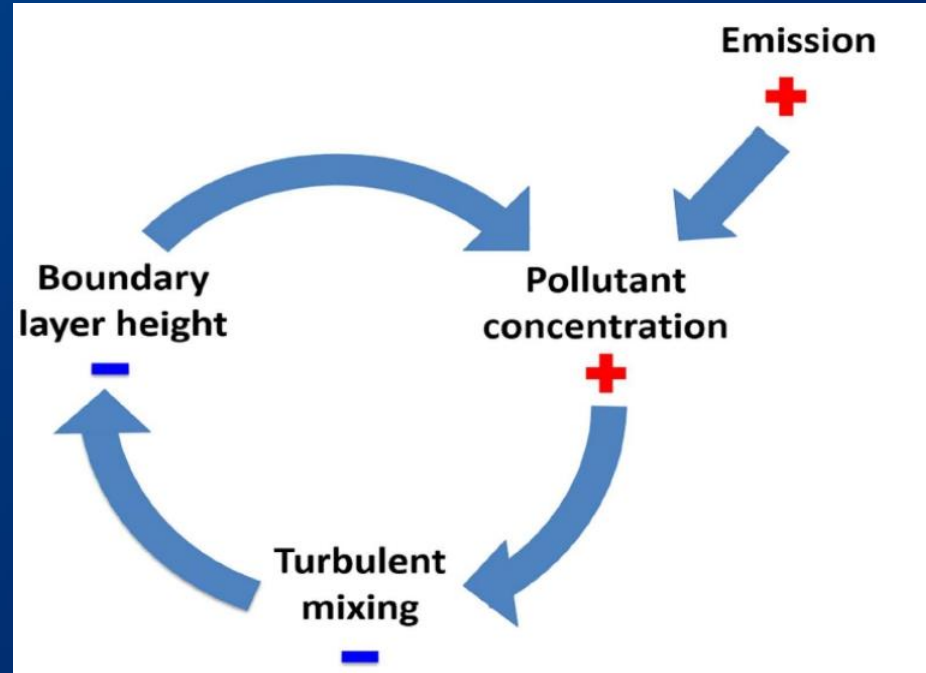




Compare UAV profile with Lidar data

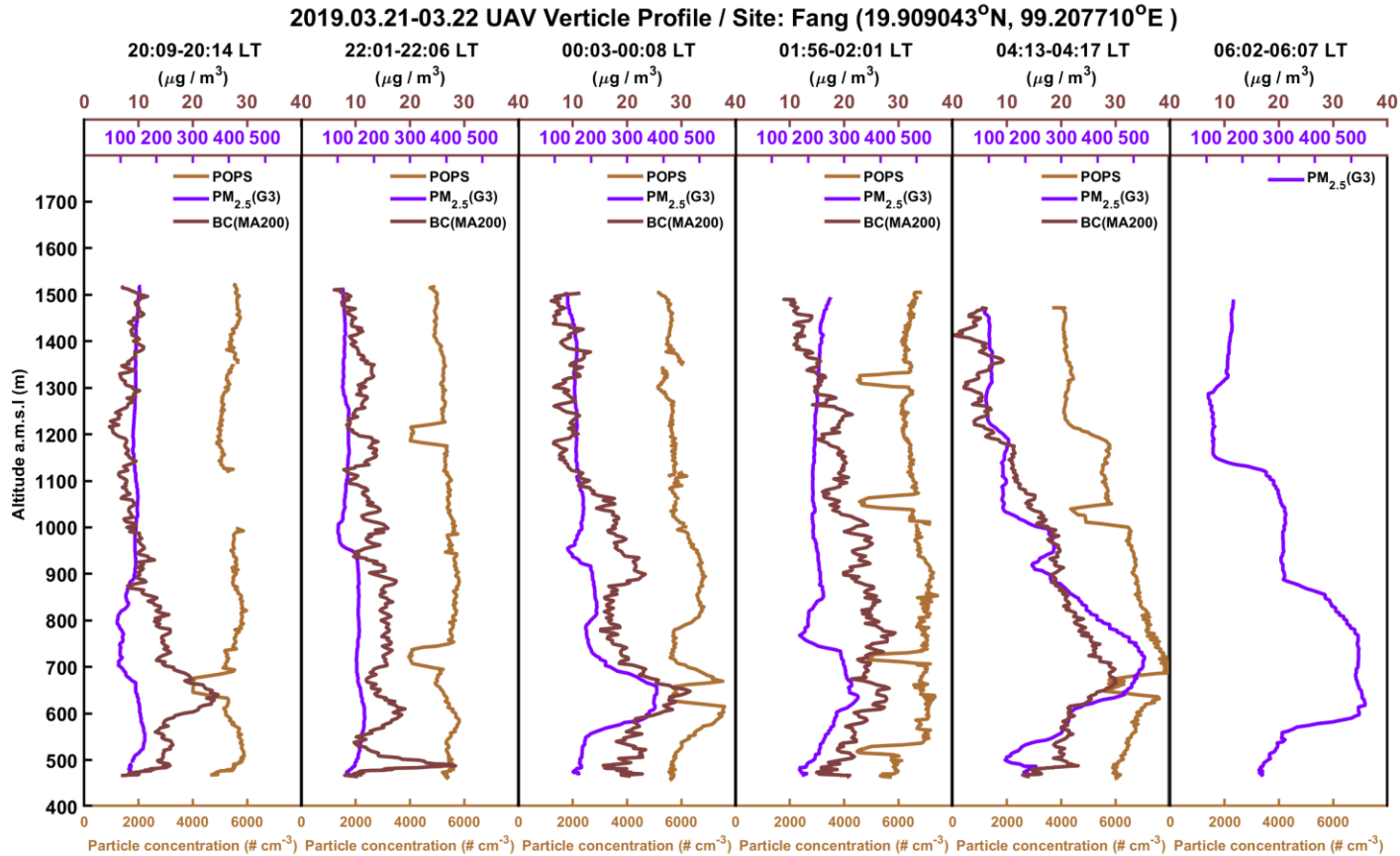
March 21-25, 2019 Aerosol-PBL Interactions

Feedback mechanism initiated by the increased aerosol concentration in the boundary layer leading to lower boundary layer height and hence elevated aerosol concentration.



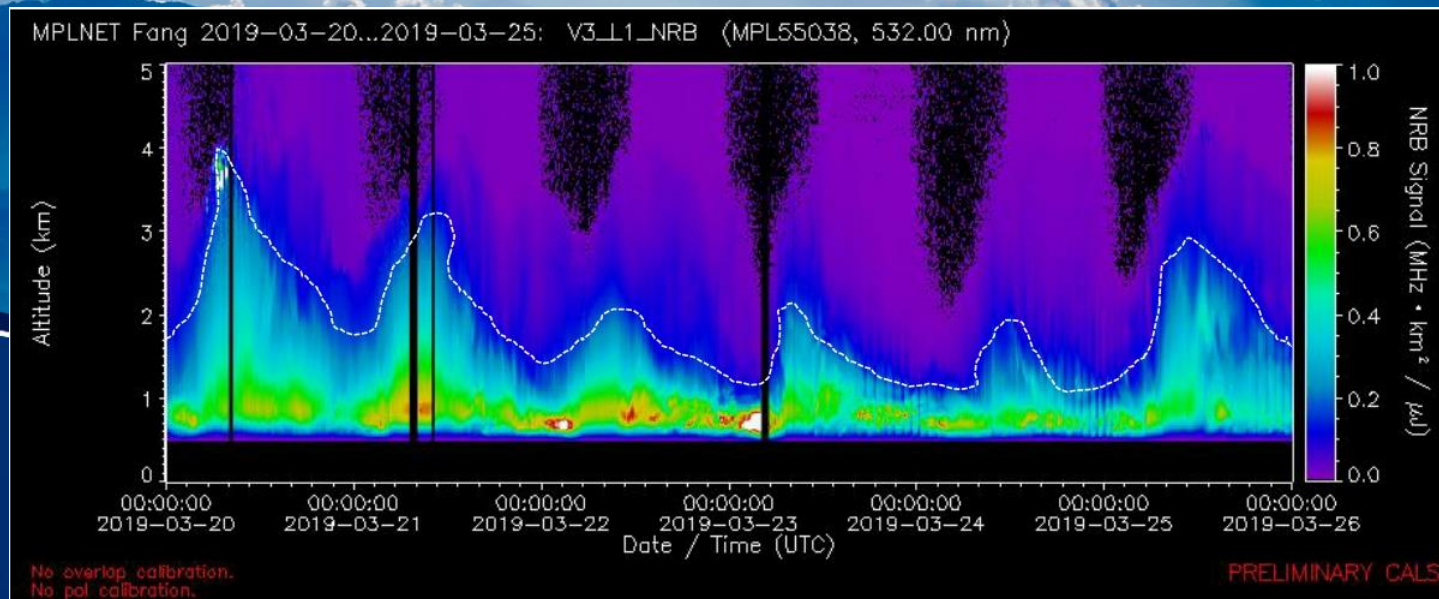
Compare UAV profile with Lidar data

March 21-25, 2019 Aerosol-PBL Interactions

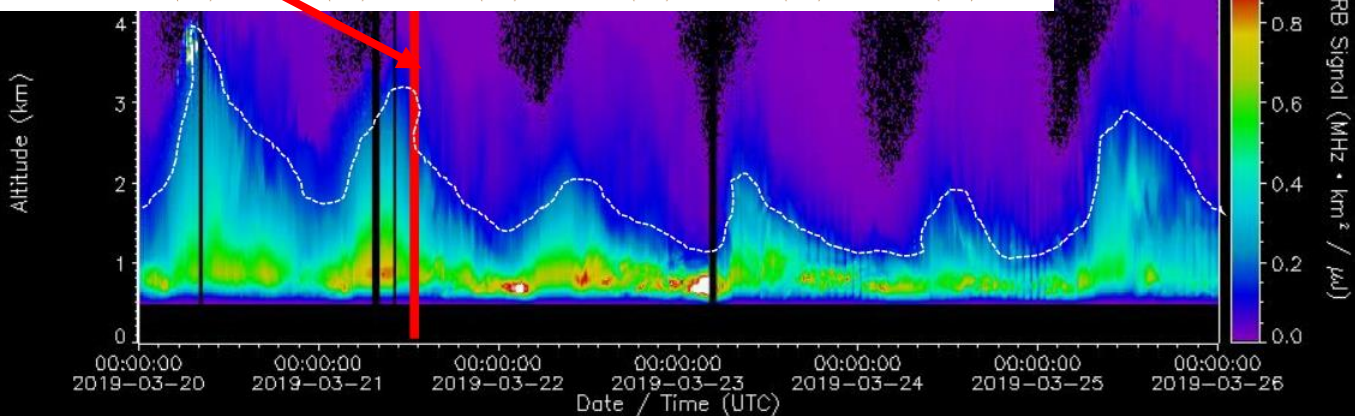
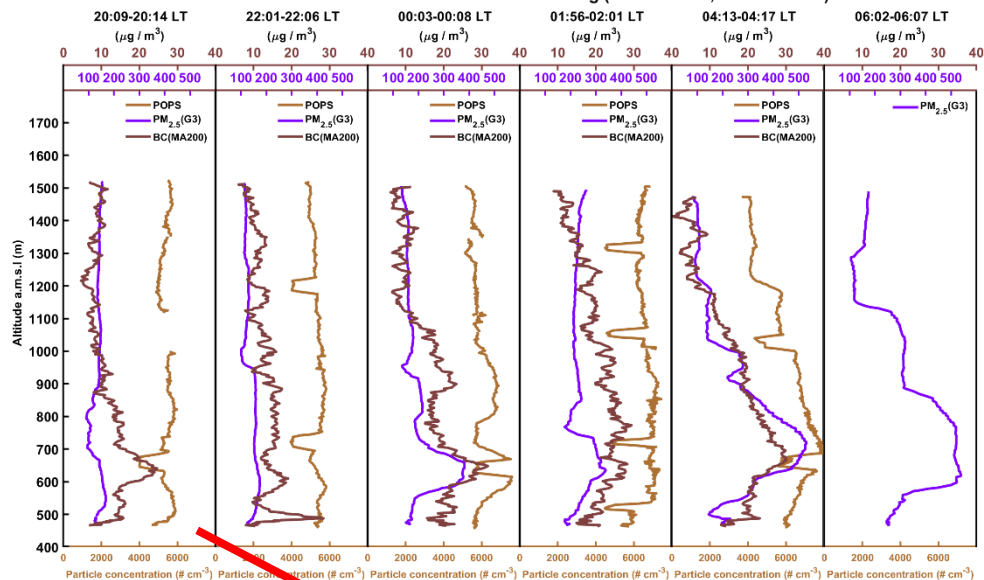


Compare UAV profile with Lidar data

May 21-25, 2019 Aerosol-PBL Interactions



2019.03.21-03.22 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)

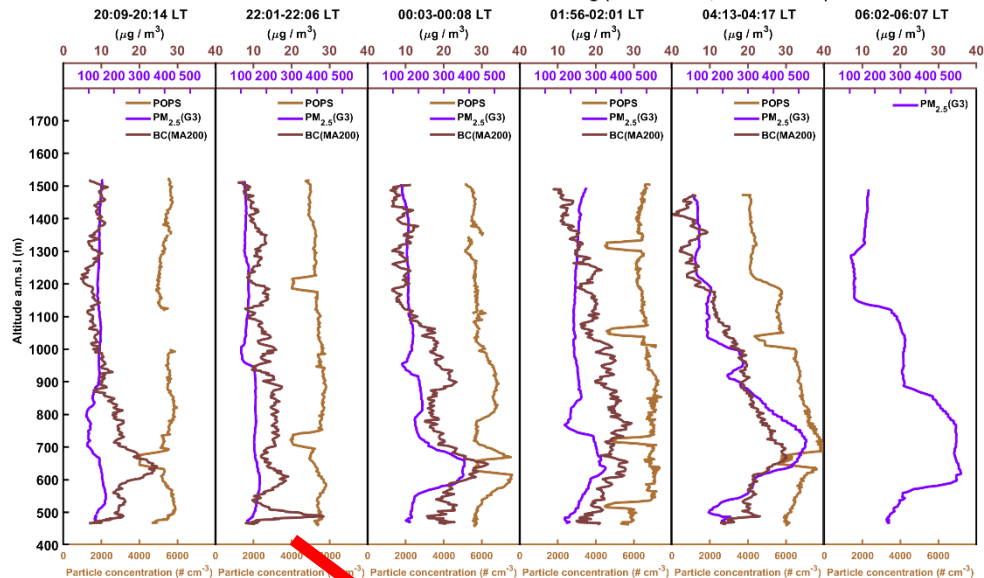


No overlap calibration.
No pol calibration.

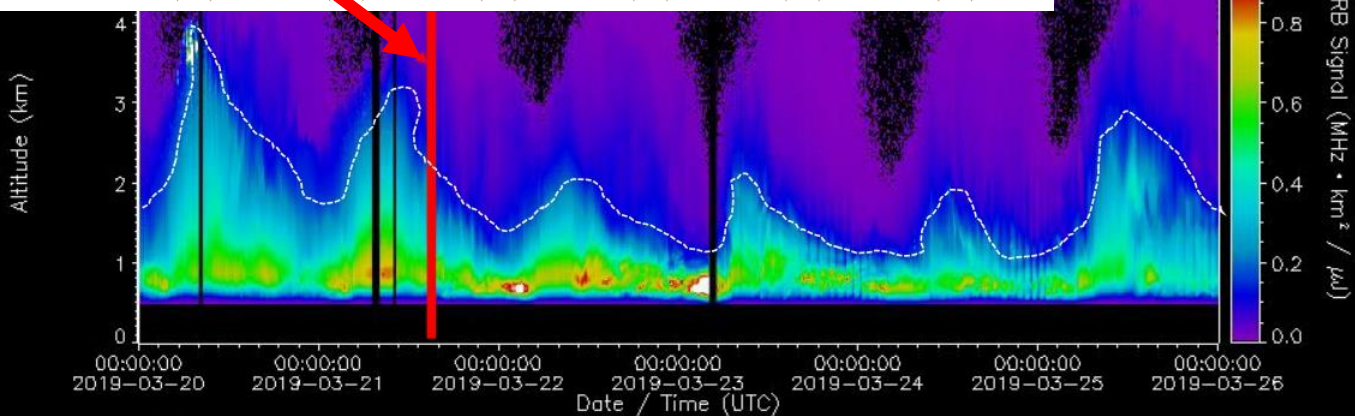
PRELIMINARY CALS

LT: March 21, 2019 (20:00)
UT: March 21, 2019 (13:00)

2019.03.21-03.22 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)



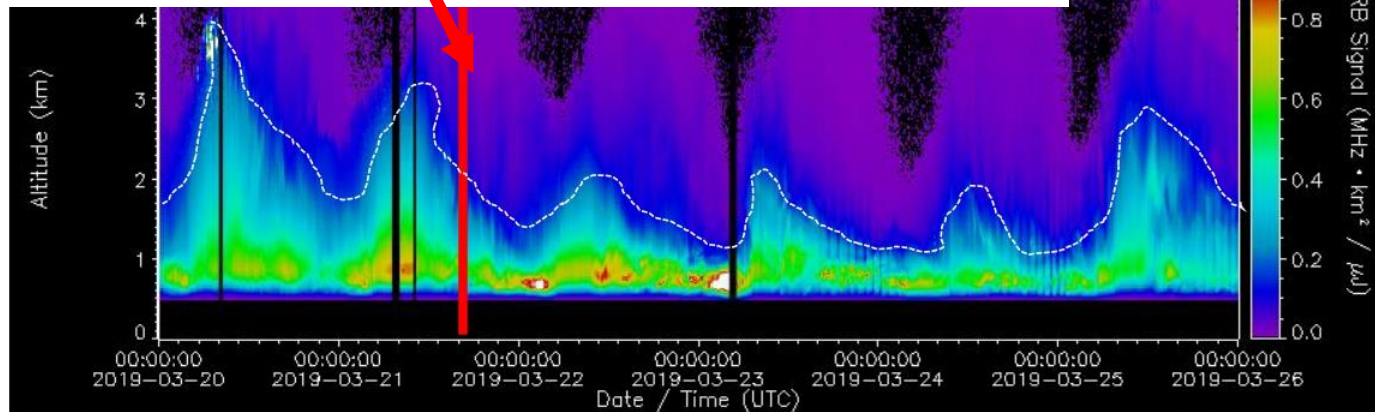
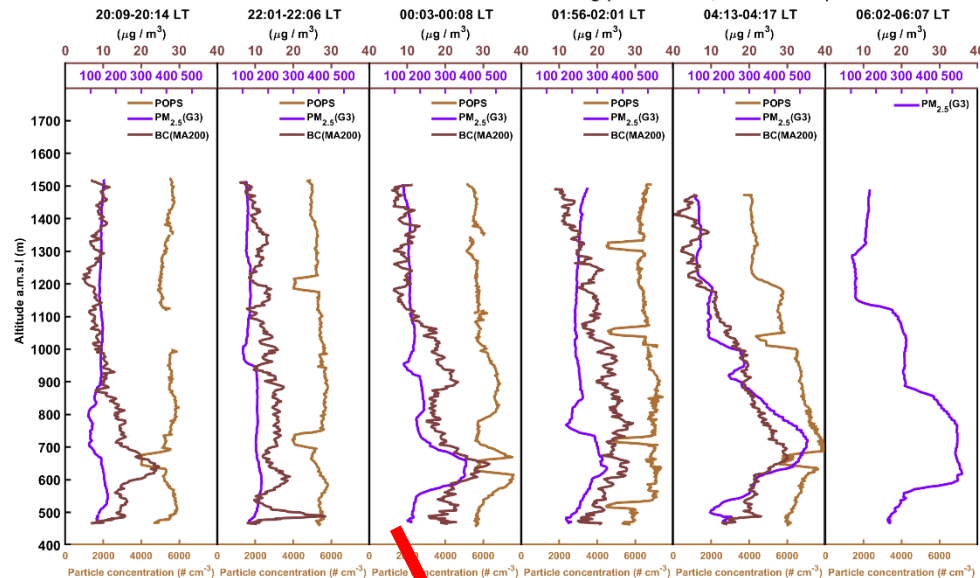
LT: March 21, 2019 (22:00)
UT: March 21, 2019 (15:00)



No overlap calibration.
No pol calibration.

PRELIMINARY CALS

2019.03.21-03.22 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)

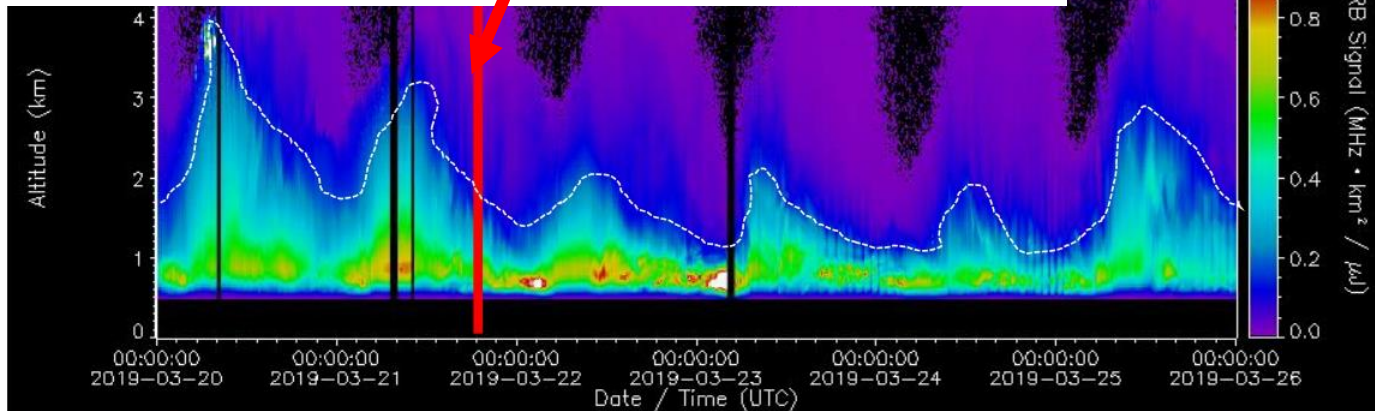
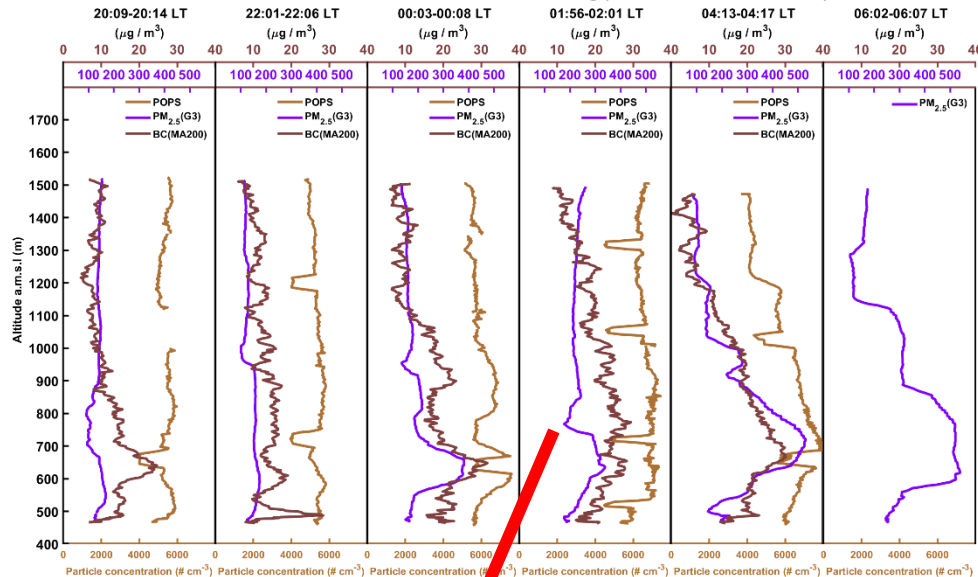


No overlap calibration.
No pol calibration.

PRELIMINARY CALS

LT: March 22, 2019 (00:00)
UT: March 21, 2019 (17:00)

2019.03.21-03.22 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)

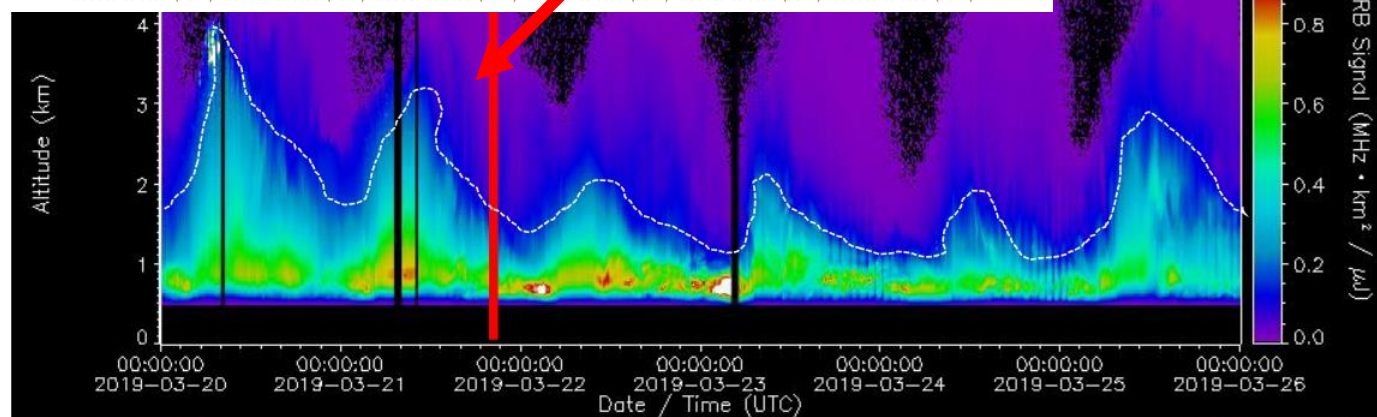
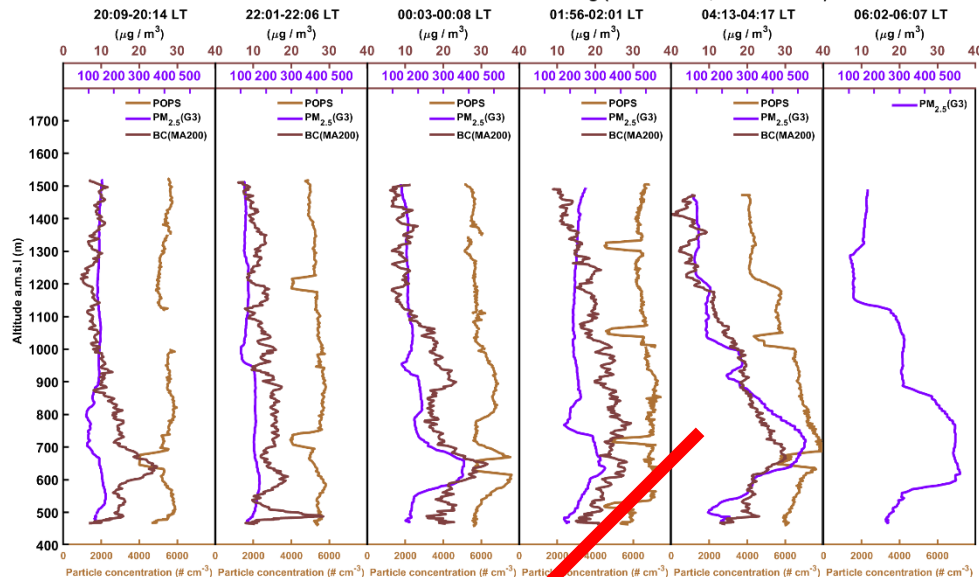


No overlap calibration.
No pol calibration.

PRELIMINARY CALS

LT: March 22, 2019 (02:00)
UT: March 21, 2019 (19:00)

2019.03.21-03.22 UAV Vertical Profile / Site: Fang (19.909043°N, 99.207710°E)



No overlap calibration.
No pol calibration.

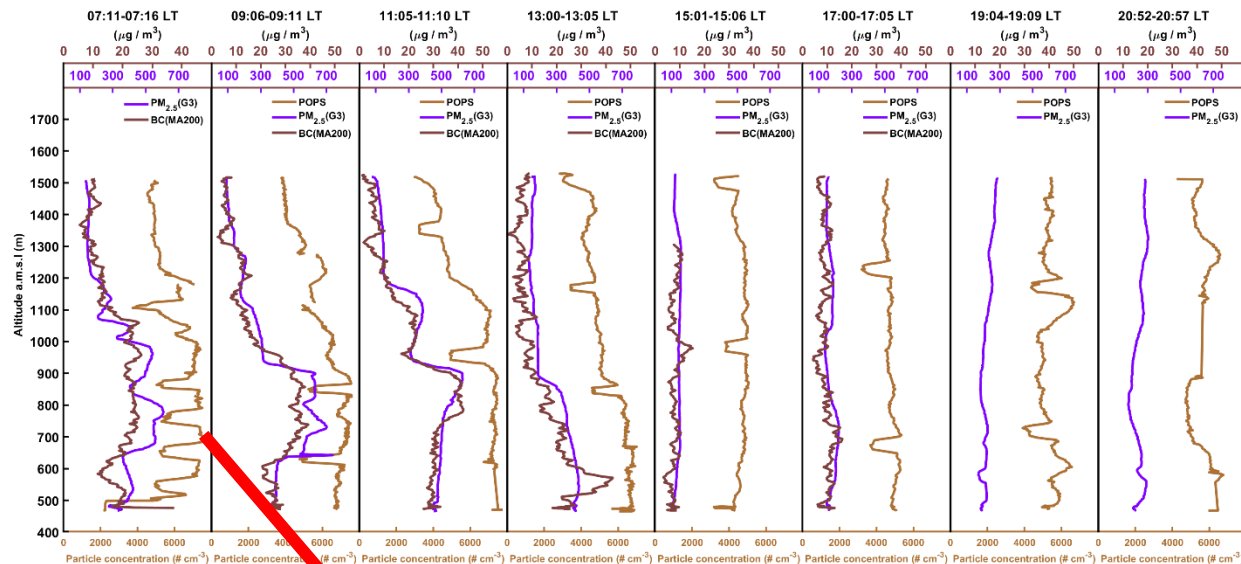
PRELIMINARY CALS

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UT: March 21, 2019 (21:00)

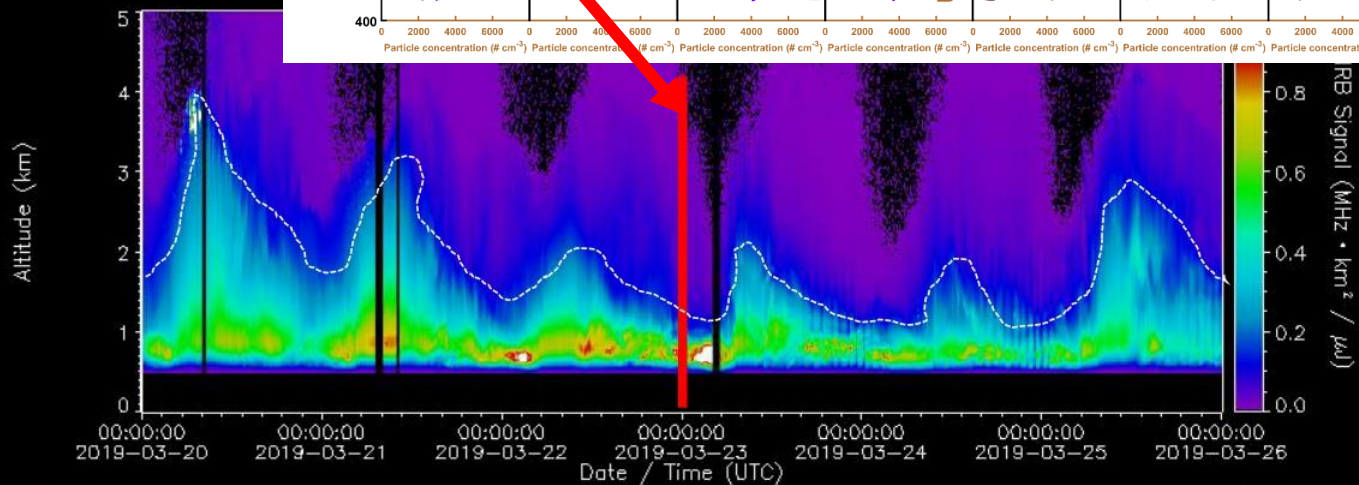
LT: March 23, 2019 (07:00)

UT: March 23, 2019 (00:00)

2019.03.23 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)



MPLNET Fang 2019-03

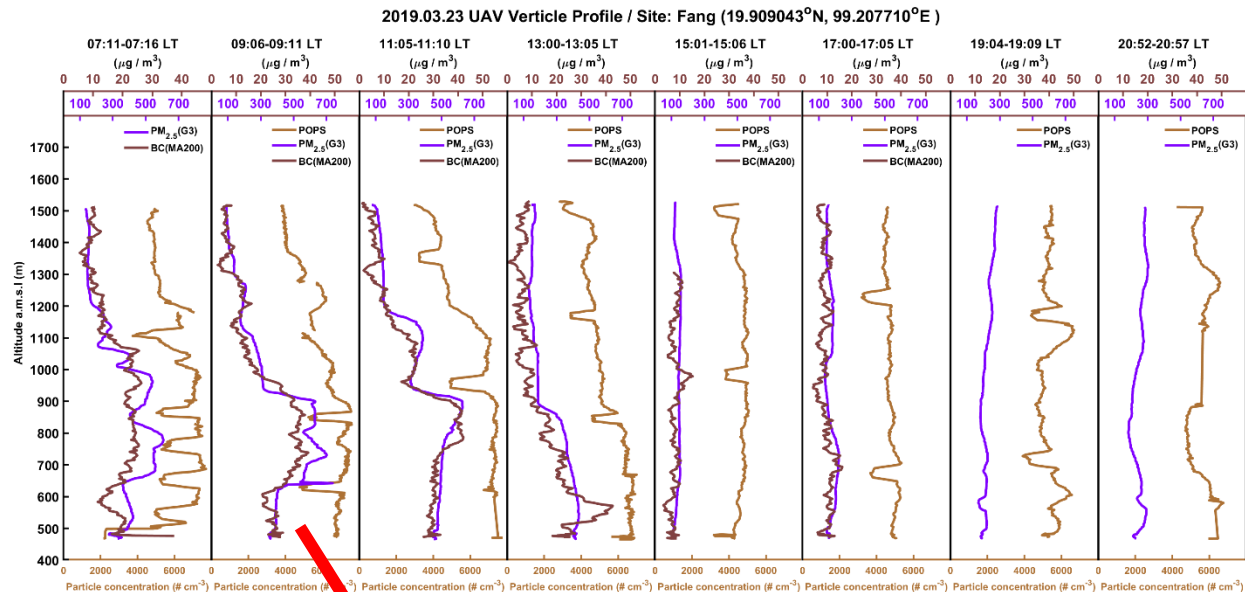


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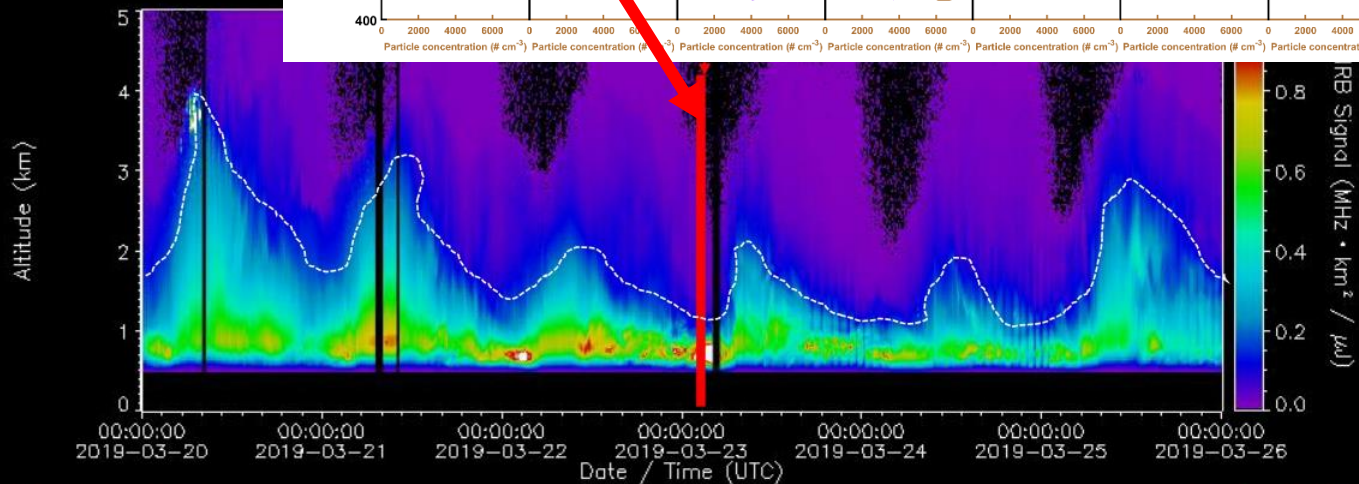
PRELIMINARY CALS

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UT: March 23, 2019 (02:00)



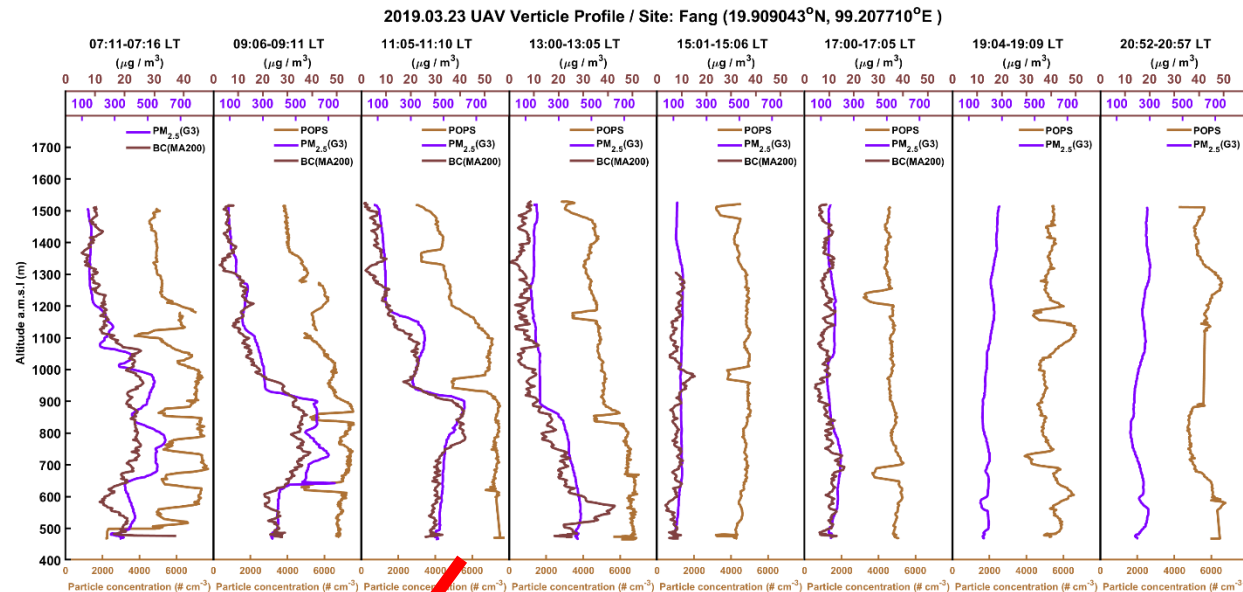
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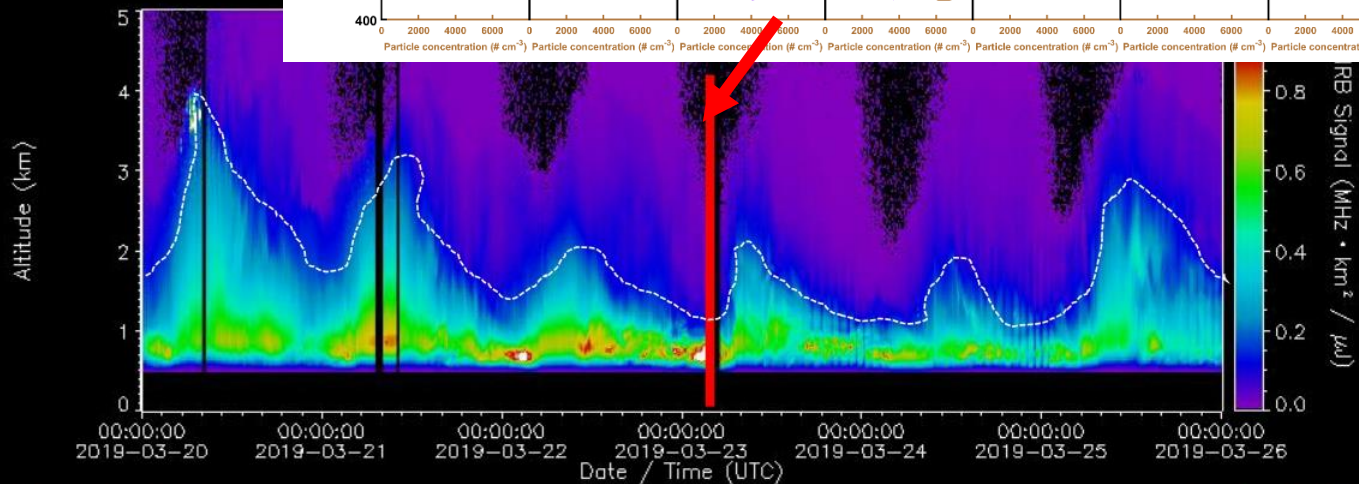
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PRELIMINARY CALS

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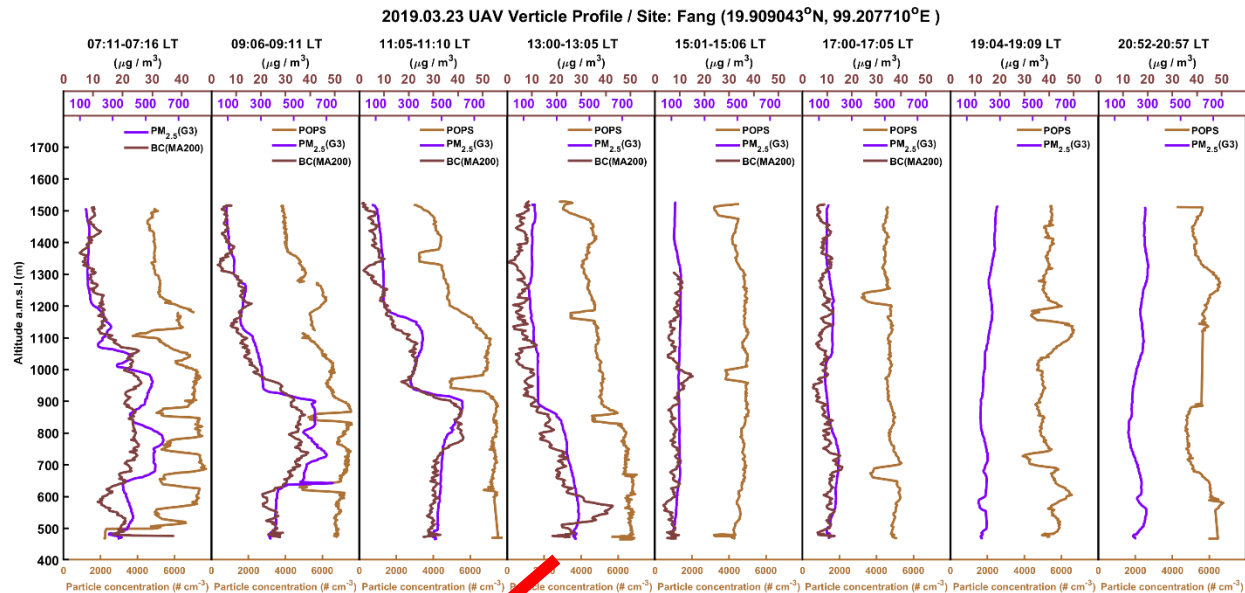
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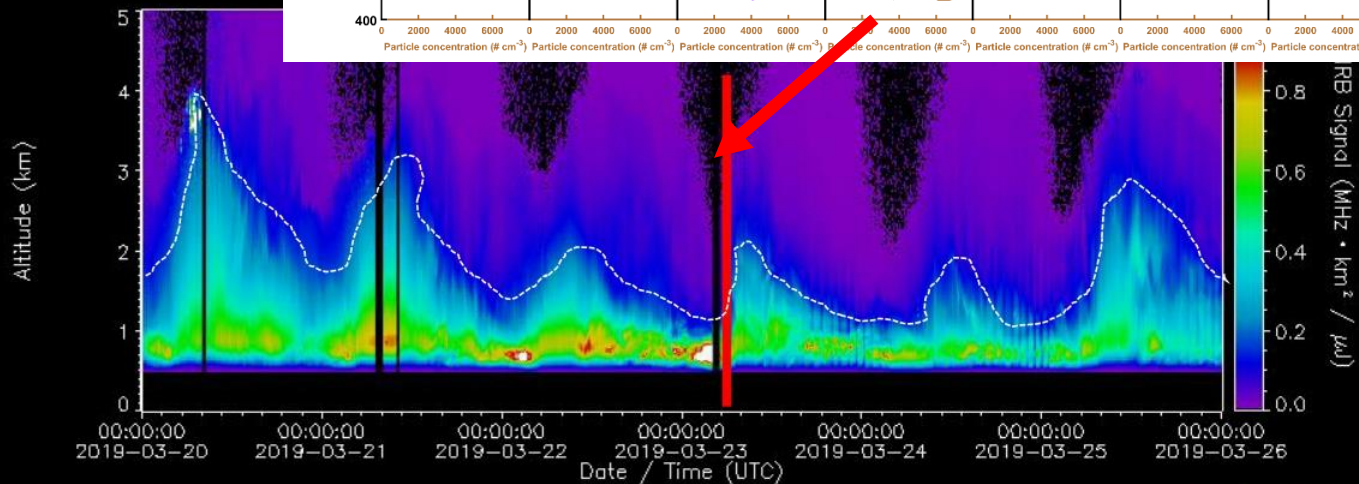
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PRELIMINARY CALS

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UT: March 23, 2019 (06:00)



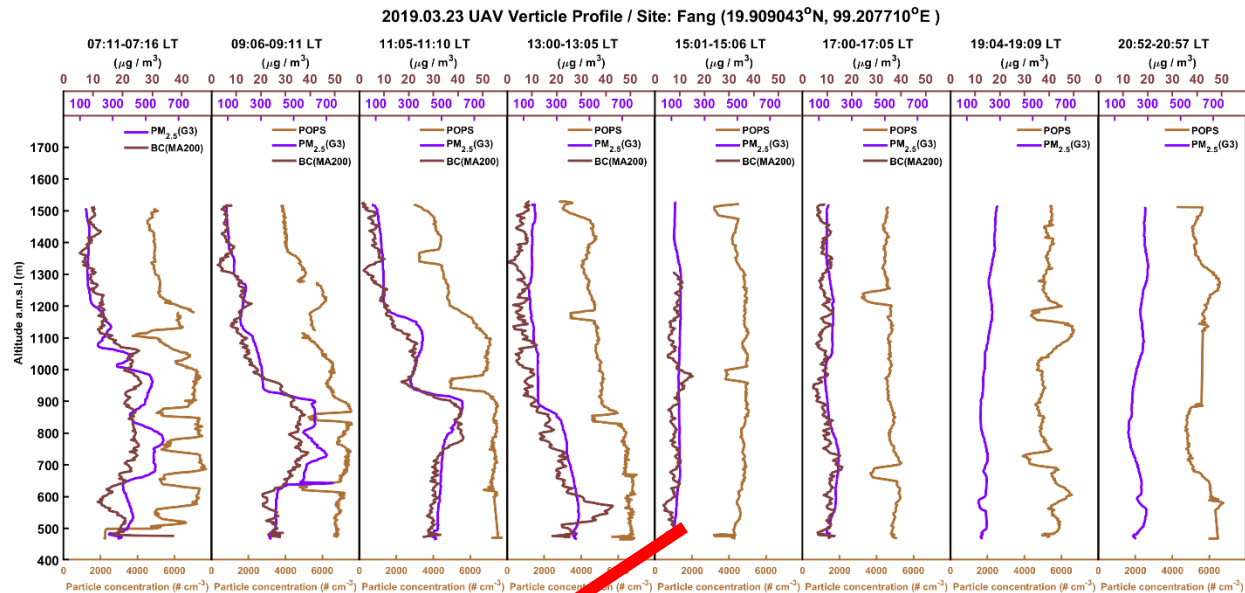
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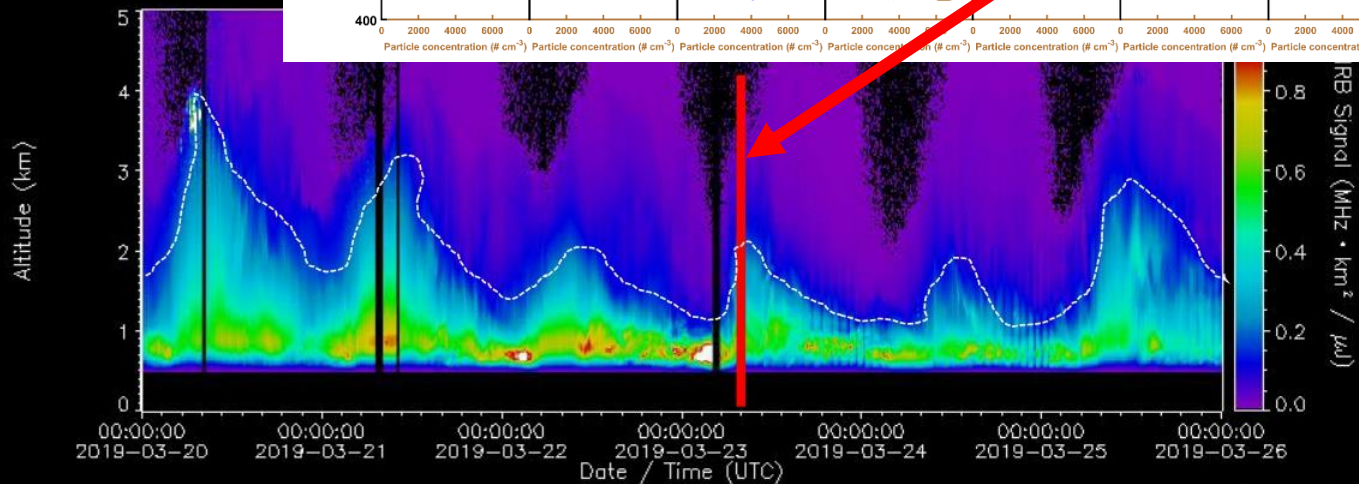
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PRELIMINARY CALS

LT: March 23, 2019 (15:00)
UT: March 23, 2019 (08:00)



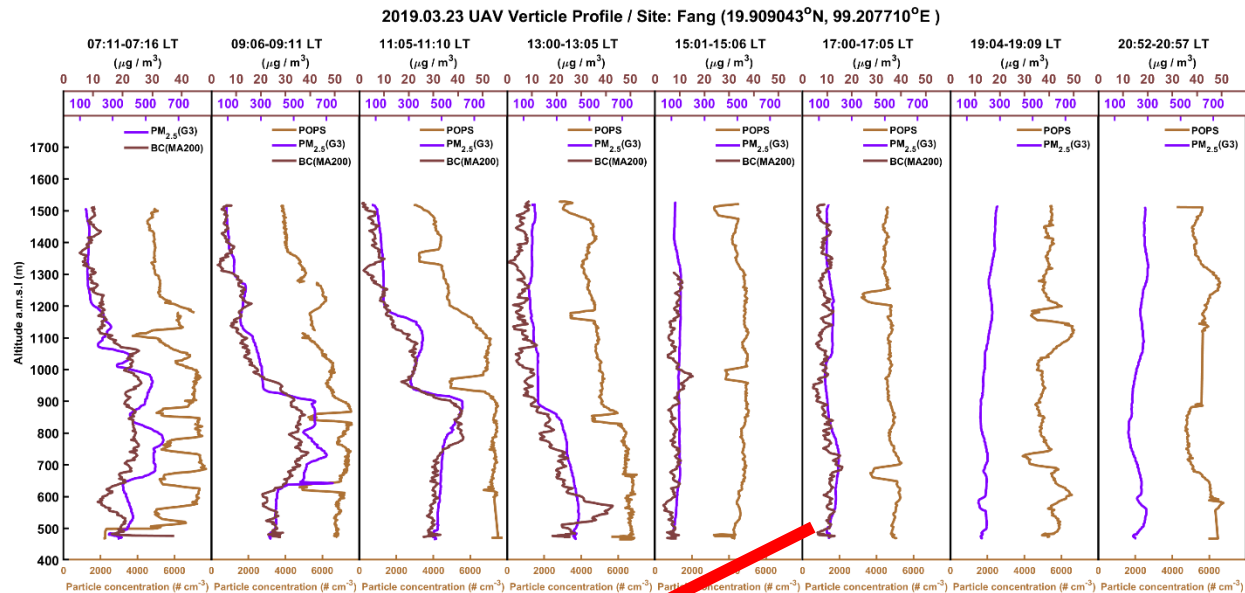
MPLNET Fang 2019-03



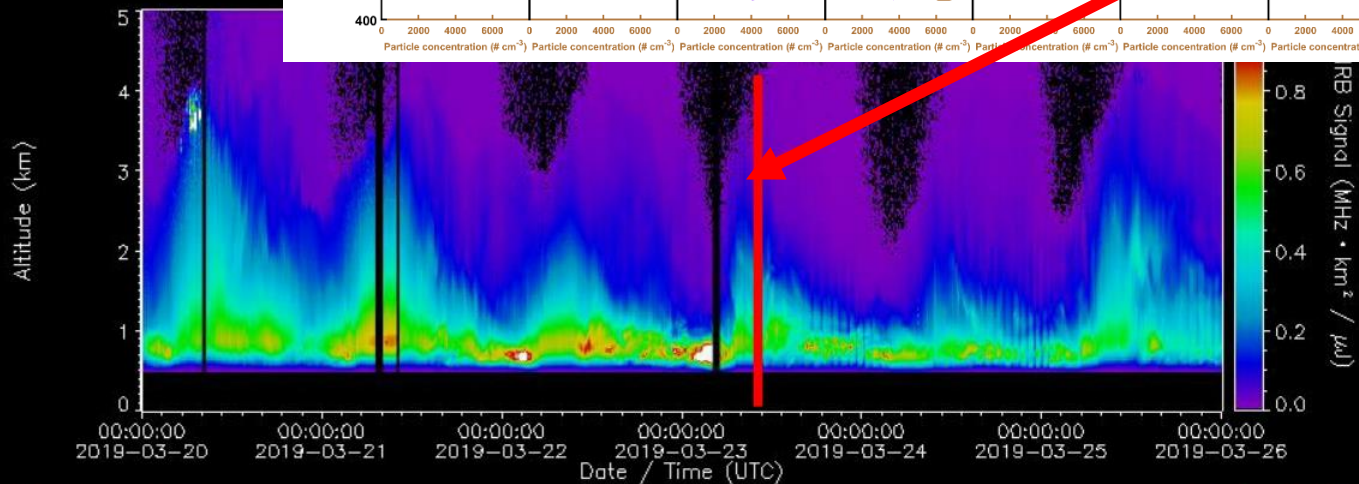
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PRELIMINARY CALS

LT: March 23, 2019 (17:00)
UT: March 23, 2019 (10:00)



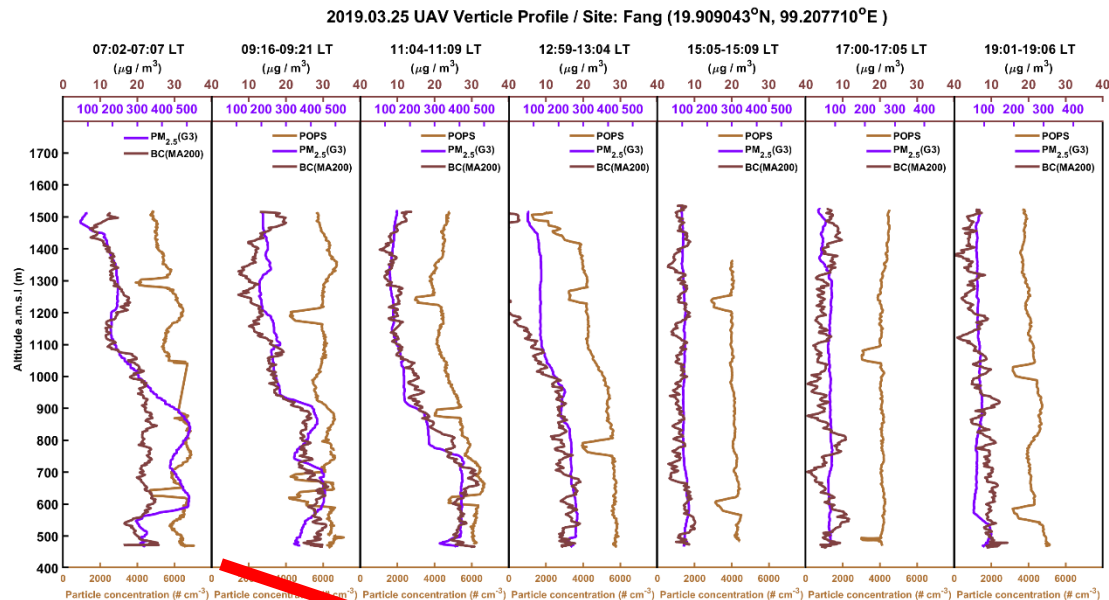
MPLNET Fang 2019-03



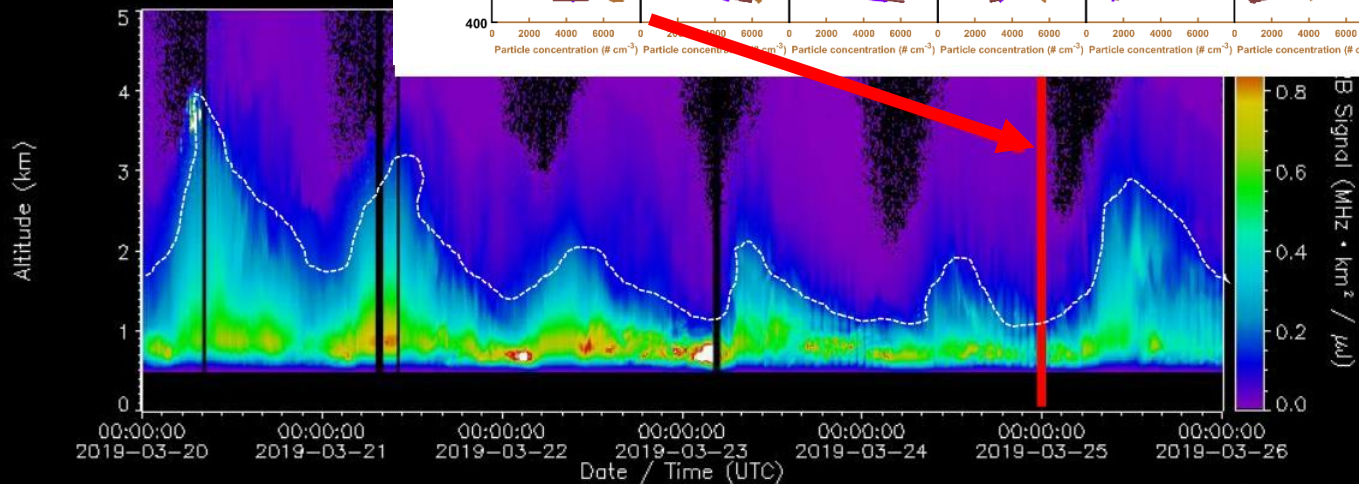
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PRELIMINARY CALS

LT: March 25, 2019 (07:00)
UT: March 25, 2019 (00:00)



MPLNET Fang 2019-03-20...2019-03-26



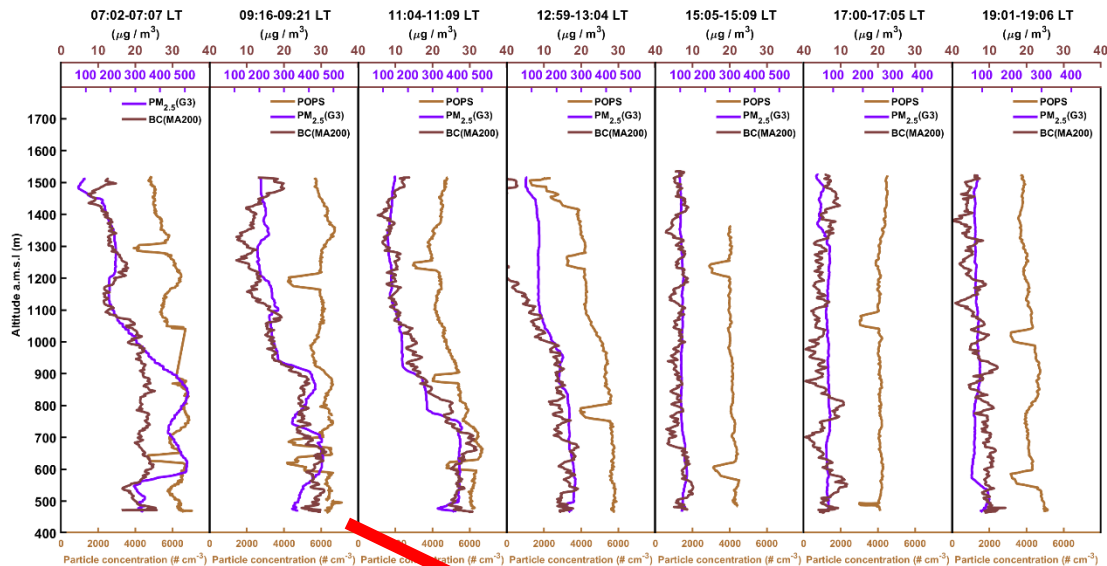
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PRELIMINARY CALS

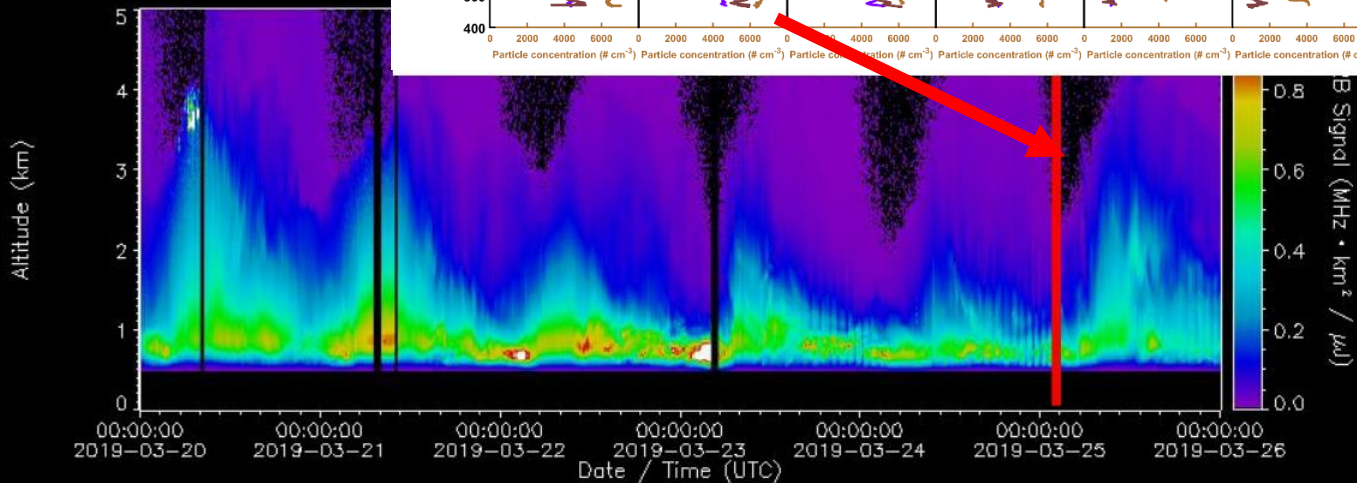


LT: March 25, 2019 (09:00)
UT: March 25, 2019 (02:00)

2019.03.25 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)



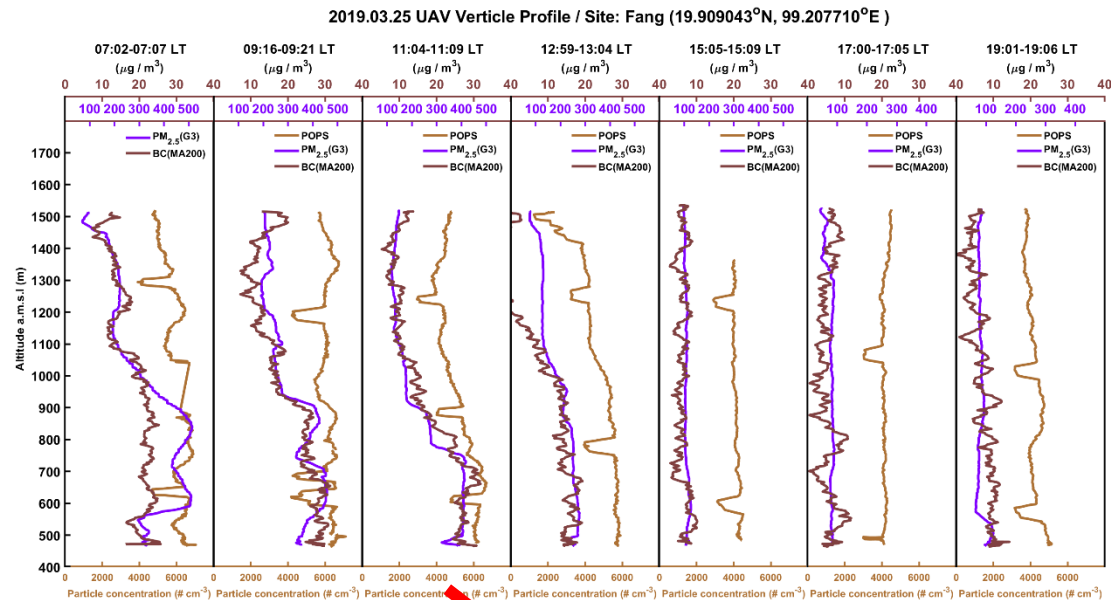
MPLNET Fang 2019-03-20...2019-03-26



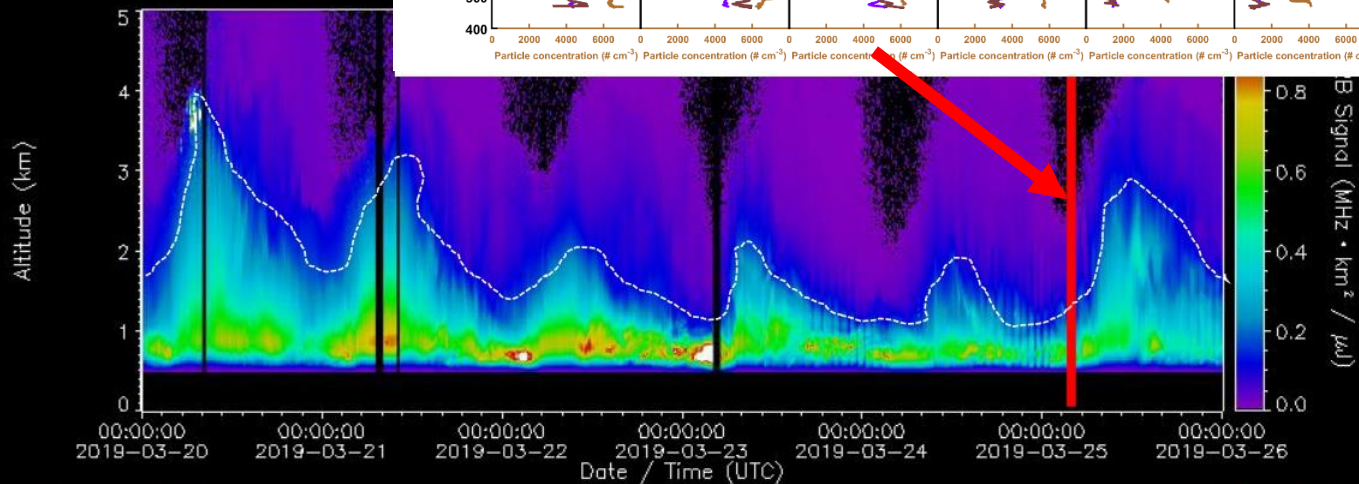
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PRELIMINARY CALS

LT: March 25, 2019 (11:00)
UT: March 25, 2019 (04:00)



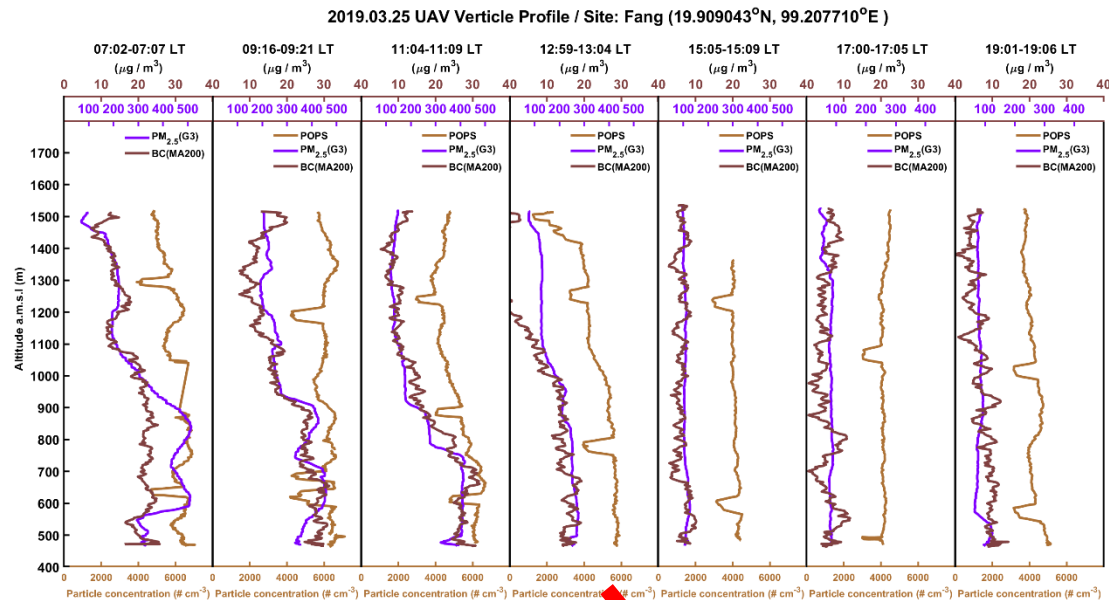
MPLNET Fang 2019-03-20...2019-03-26



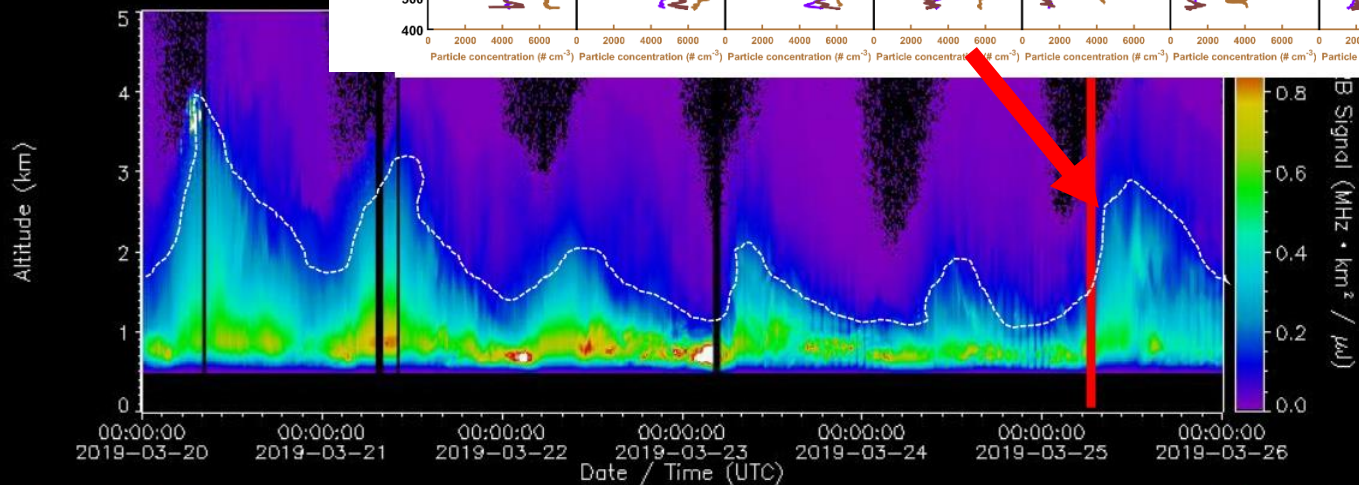
No overlap calibration.
No pol calibration.

PRELIMINARY CALS

LT: March 25, 2019 (13:00)
UT: March 25, 2019 (06:00)



MPLNET Fang 2019-03-20



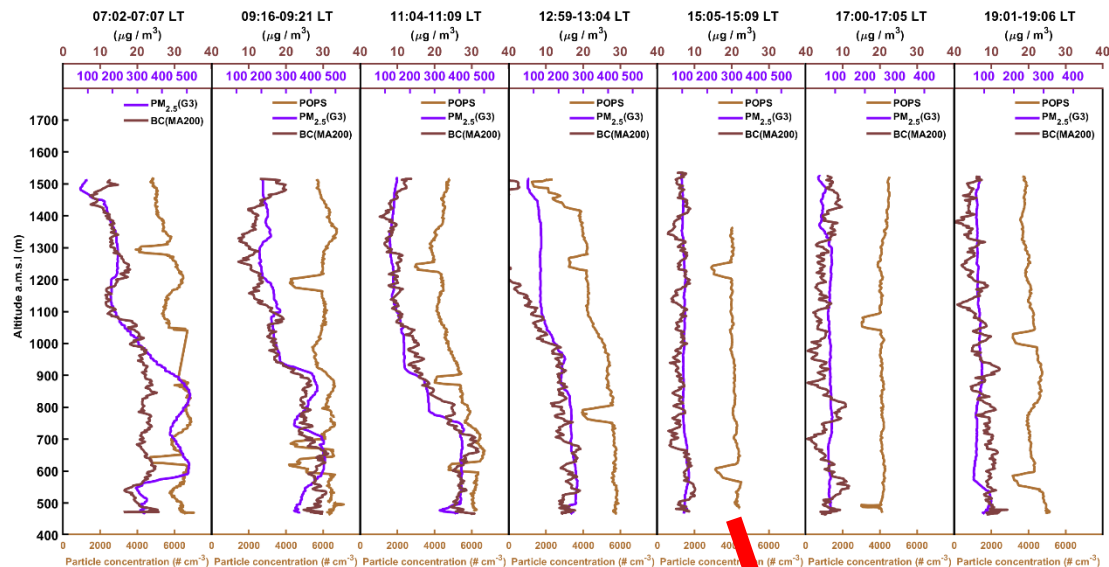
No overlap calibration.
No pol calibration.

PRELIMINARY CALS

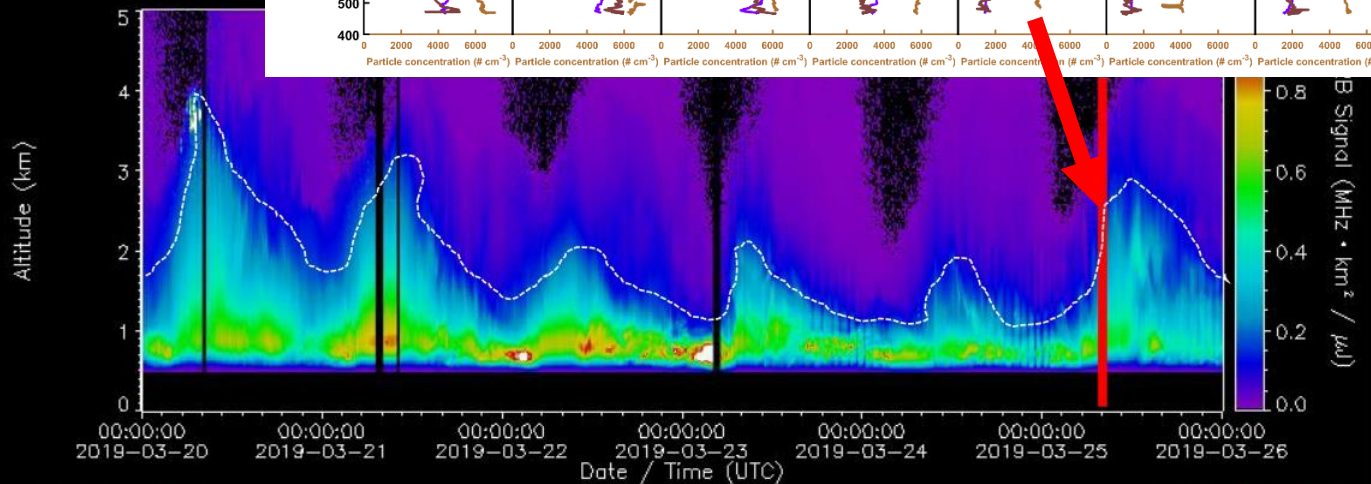
LT: March 25, 2019 (15:00)

UT: March 25, 2019 (08:00)

2019.03.25 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)



MPLNET Fang 2019-0

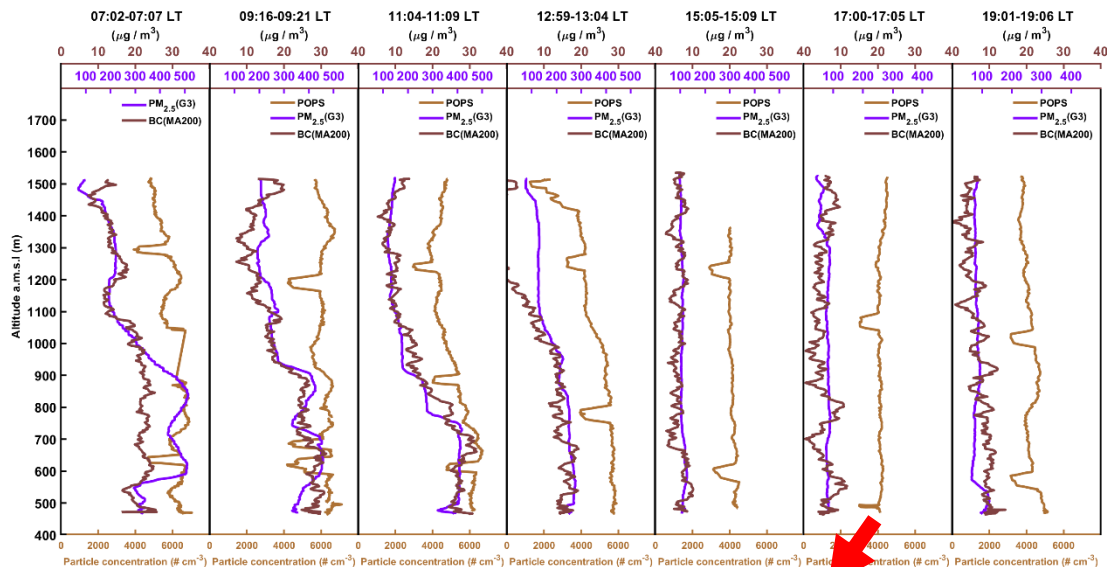


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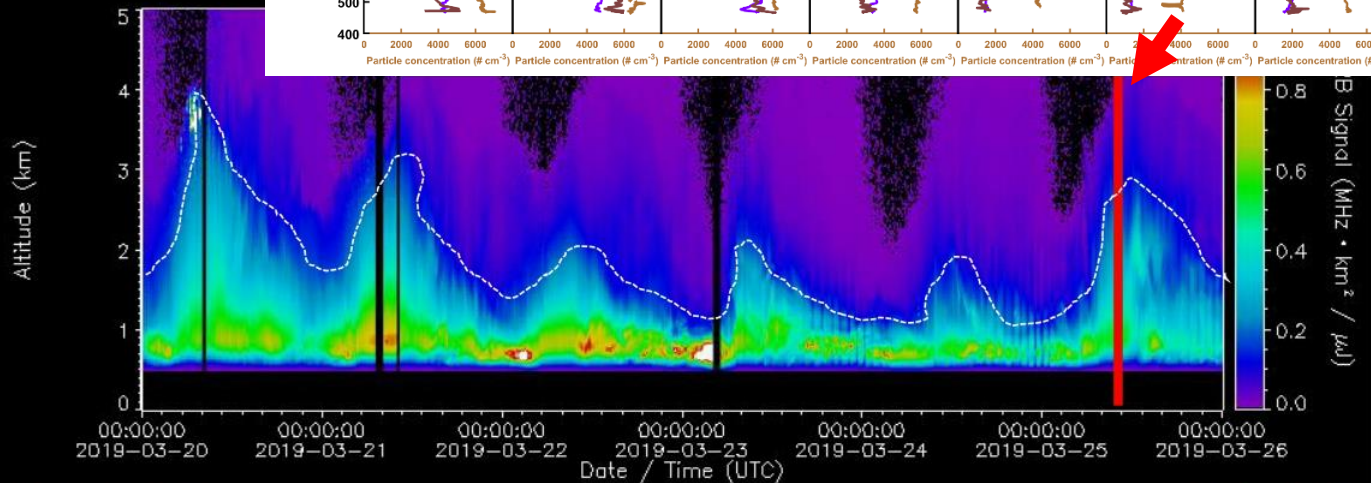
PRELIMINARY CALS

LT: March 25, 2019 (17:00)
UT: March 25, 2019 (10:00)

2019.03.25 UAV Verticle Profile / Site: Fang (19.909043°N, 99.207710°E)



MPLNET Fang 2019-0

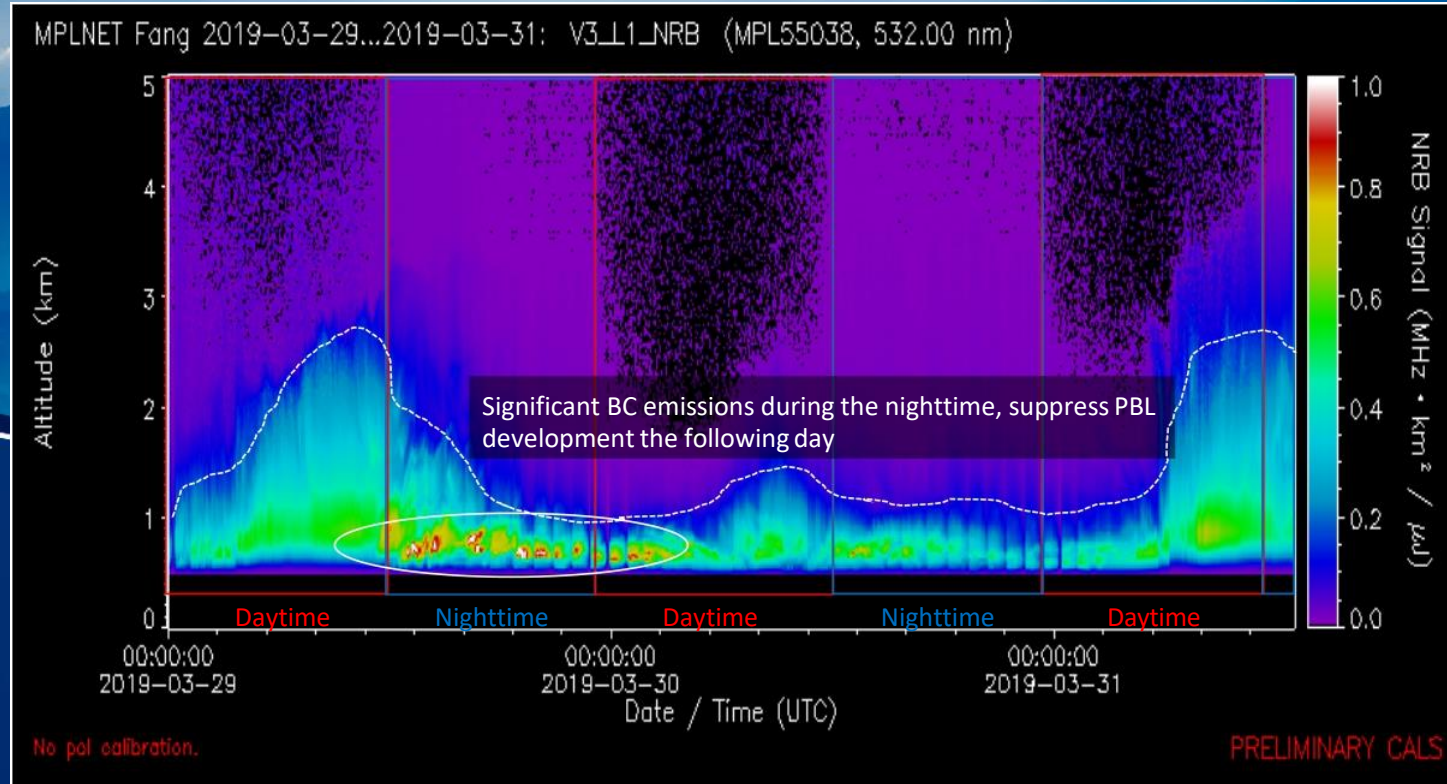


No overlap calibration.
No pol calibration.

PRELIMINARY CALS

Compare UAV profile with Lidar data

May 21-25, 2019 Aerosol-PBL Interactions



Thank you!!

